

ON THE STABILITY OF THE ALTERNATIVE METHOD

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Abstract. The stability of the alternative method is investigated. An optimization of the volume of computation for the numerical approximation of a solution of the equation $Lu = Nu$ is also given.

1. Introduction

The stability of the fixed point iteration procedures has been investigated by A.M. Harder and T.L. Hicks [1]:

Definition 1. Let (X, d) be a metric space, $T : X \rightarrow X$, $x_0 \in X$ and the iteration procedure $x_{n+1} = f(T, x_n)$. If $x_n \rightarrow p$, where p is a fixed point of T , let $y_n \in X$ and $\varepsilon_n = d(y_{n+1}, f(T, y_n))$. If $\varepsilon_n \rightarrow 0$ implies $y_n \rightarrow p$ then the iteration procedure f is T -stable relating to T .

If T is a contraction, a theorem of Ostrowski [1] shows that the iteration procedure $f(T, x_n) = Tx_n$ is T -stable:

Theorem 1. Let $T : X \rightarrow X$ be a contraction on the complete metric space (X, d) . Let p a fixed point of T , $x_0 \in X$; $x_{n+1} = Tx_n$, $n = 0, 1, \dots$ be. Let $y_n \in X$ and $\varepsilon_n = d(y_{n+1}, Ty_n)$, $n = 0, 1, \dots$. Then

1. $d(p, y_{n+1}) \leq (1 - k)^{-1}(\varepsilon_n + kd(y_n, y_{n+1}))$
2. $d(p, y_{n+1}) \leq d(p, x_{n+1}) + k^{n+1}d(x_0, y_0) + \sum_{i=0}^n k^{n-i}\varepsilon_i$
3. $y_n \rightarrow p$ if and only if $\varepsilon_n \rightarrow 0$.

If X is a Banach space, $E : X_E \rightarrow X$ is a linear operator and $N : X_N \rightarrow X$ is a nonlinear operator, let us consider the equation $Eu = Nu$, $u \in X_E \cap X_N$.

If E is an invertible operator, this equation is equivalent to $u = E^{-1}Nu$, a fixed point problem for $T = E^{-1}N$. If T is a contraction, Theorem 2 applies. If T is not a contraction or E is not invertible, the equation $Eu = Nu$ is studied by the alternative (Lyapunov-Schmidt) method. Using an idea of Sanchez [2] it is easy to conclude that the alternative method is T -stable. An optimization of the volume of computation for the numerical approximation of the solution of the equation $Eu = Nu$ by the alternative method is also given.

2. The stability of the alternative method

Let X be a Banach space, $E : X_E \rightarrow X$ a linear operator, $N : X_N \rightarrow X$ a nonlinear operator and we suppose that

- a): there exists a projection $P : X \rightarrow X$ such that $X = R(P) \oplus R(I - P)$ and $PE = EP$
- b): there exists $H : R(I - P) \rightarrow R(I - P)$, a linear operator such that

$$\begin{aligned} H(I - P)Eu &= (I - P)u \text{ for all } u \in X_E \\ EH(I - P)Nu &= (I - P)Nu \text{ for all } u \in X_N \end{aligned}$$

- c): all the fixed points of $P + H(I - P)N$ are in X_E .

Theorem 2. $Eu = Nu$ if and only if

$$\begin{aligned} (I - P)u &= H(I - P)Nu \\ P(EPu - Nu) &= 0 \end{aligned}$$

Let $D : R(P) \rightarrow R(P)$ be a linear, invertible and with bounded inverse operator. For $a, b > 0$ we define

$$C = \{(v, w) \mid v \in R(P), \|v - v_0\| \leq a, w \in R(I - P), \|w\| \leq b\}$$

where $v_0 \in R(P)$ is an approximation of the solution of the equation $Eu = Nu$. On C we define $\|(v, w)\| = \|v\| + \|w\|$. Let $p \in \mathbb{N}$, $u = v + w$ where $(v, w) \in C$, $w^0 = w$, $w^i = H(I - P)N(v + w^{i-1})$, for $i = 1, 2, \dots, p + 1$ and $W = w^{p+1}$. Let $V = v - D^{-1}P(Ev - N(v + W))$. We define an operator on C by $T(v, w) = (V, W)$. We remark that in the paper of Sanchez [2], $p = 0$.

Theorem 3. *If*

1. *there exists $\eta \geq 0$ such that $(v, w) \in C$ implies $\|N(v + w)\| \leq \eta$*
2. *$H(I - P)$ is a bounded operator and $\|H(I - P)\| \leq b/\eta$*
3. *there exists $\sigma \geq 0$ such that $\|D^{-1}\| \sigma < 1$ and if $(v_1, w), (v_2, w) \in C$ then*

$$\|D(v_1 - v_2) - P(Ev_1 - N(v_1 + w) - Ev_2 + N(v_2 + w))\| \leq \sigma \|v_1 - v_2\|$$
4. *there exists $\gamma \geq 0$ such that $(v_0, w) \in C$ implies*

$$\|D^{-1}P(Ev_0 - N(v_0 + w))\| \leq \gamma \leq (1 - \|D^{-1}\| \sigma)a,$$

then T applies C into C .

Proof. From $(v, w) \in C$ we have $(v, w^k) \in C$ for all k thus

$$\|W\| = \|H(I - P)N(v + w^p)\| \leq b/\eta \cdot \eta = b$$

We have also

$$\begin{aligned} \|V - v_0\| &\leq \|D^{-1}\| \|D(v - v_0) - P(Ev - N(v + W)) - P(Ev_0 - N(v_0 + W))\| \leq \\ &\leq \|D^{-1}\| \sigma \|v - v_0\| + (1 - \|D^{-1}\| \sigma)a \leq a \end{aligned}$$

Theorem 4. *If the conditions 1-4 of theorem 4 hold and*

- 5) *there exists $L > 0$ such that if $u_i = v_i + w_i$, $(v_i, w_i) \in C$, $i = 1, 2$ then*

$$\|Nu_1 - Nu_2\| \leq L \|u_1 - u_2\|$$
- 6) $\mu = \|D^{-1}\| \sigma + (1 + \|D^{-1}P\| L)(\theta + \dots + \theta^{p+1}) < 1$, *where $\theta = \|H(I - P)\| L$,*
then T is a contraction.

Proof. Let $T(v_i, w_i) = (V_i, W_i)$, $i = 1, 2$. We have

$$\|W_1 - W_2\| \leq \|H(I - P)\| L(\|v_1 - v_2\| + \|w_1^p - w_2^p\|)$$

But

$$\|w_1^p - w_2^p\| \leq (\|v_1 - v_2\| + \|w_1^{p-1} - w_2^{p-1}\|) \|H(I - P)\| L$$

thus

$$\|W_1 - W_2\| \leq \|v_1 - v_2\| (\theta + \dots + \theta^{p+1}) + \theta^{p+1} \|w_1 - w_2\|$$

Consequently,

$$\begin{aligned} \|V_1 - V_2\| + \|W_1 - W_2\| &\leq [\|D^{-1}\| \sigma + (1 + \|D^{-1}P\| L)(\theta + \dots + \theta^{p+1})] \|v_1 - v_2\| + \\ &\quad + (1 + \|D^{-1}P\| L)\theta^{p+1} \|w_1 - w_2\| \leq \mu (\|v_1 - v_2\| + \|w_1 - w_2\|) \end{aligned}$$

Hence T has an unique fixed point $(v, w) = (V, W) \in C$ that may be obtained by the iteration procedure $(v_{k+1}, w_{k+1}) = T(v_k, w_k)$.

Theorem 5. *If the conditions of the theorems 4,5 hold, then $u = V + W$ is a solution of the equation $Eu = Nu$.*

Proof. We have $w^1 = W, \dots, w^p = W$, that is $W = H(I - P)N(V + W)$. Then $V = V - D^{-1}P(EV - N(V + W))$ and consequently, $P(EV - N(V + W)) = 0$ and $Eu = Nu$ from theorem 3.

3. The optimization of the numerical computation of the solutions

We approximate the 2π -periodic solutions of the equation

$$-u''(t) = f(t, u(t))$$

Let X be the Banach space of 2π -periodic, continuous functions $u : \mathbb{R} \rightarrow \mathbb{R}$, $\|u\| = \sup_{t \in [0, 2\pi]} |u(t)|$, f a continuous, 2π -periodic function on t , differentiable in u , with locally bounded derivative. Let $X_E = H^2(0, 2\pi)$, $X_N = X$, $Eu = -u''$, $Nu = f(\cdot, u)$.

If $u \in X$ let

$$\frac{a_0}{2} + \sum_{k=1}^{\infty} (a_k \cos kt + b_k \sin kt)$$

his Fourier series. We define, for $m \in \mathbb{N}$,

$$P_m u = \frac{a_0}{2} + \sum_{k=1}^m (a_k \cos kt + b_k \sin kt)$$

$$H(I - P_m)u = \sum_{k=m+1}^{\infty} (a_k \cos kt + b_k \sin kt)/k^2$$

From [3] we have $\|H(I - P_m)\| \rightarrow 0$ when $m \rightarrow \infty$. For an approximation $v_0 \in P_m X$ we define the sequence $w^s = H(I - P_m)N(v + w^{s-1})$, $w^0 = 0$, for $s = 1, 2, \dots, p + 1$. If m is sufficiently great then $(v, w^s) \in C$ if $\|v - v_0\| \leq a$, $v \in P_m X$. The second

equation $P(EPu - Nu) = 0$ becomes an equation for the Fourier coefficients of v , $F(c) = 0$, where $c = (a_0/2, a_1, b_1, \dots, a_m, b_m)$.

If the Jacobian $J(c_0)$ of F in v_0 is invertible, let $D = J(c_0)$ and we use a theorem of Urabe [4]:

Theorem 6. *Let us consider the system $F(c) = 0$, $F = (F_1, \dots, F_n)$, $c = (c_1, \dots, c_n)$ for $n \in \mathbb{N}$. We suppose that $F \in C^1(\Omega)$ and that there exists $k \in [0, 1)$ and $\delta > 0$ such that*

1. $\Omega_\delta = \{c \in P_m X \mid \|c - c_0\| \leq \delta\} \subset \Omega$
2. $\|J(c) - J(c_0)\| \leq k/M$
3. $Mr/(1 - k) \leq \delta$

where $M \geq \|J^{-1}(c_0)\|$, $r \geq \|F(c_0)\|$.

Then the system $F(c) = 0$ has an unique solution $\bar{c} \in \Omega_\delta$ and $\|\bar{c} - c_0\| \leq Mr/(1 - k)$.

For a sufficiently great m the conditions of theorems 4,5 are consequences of the hypothesis of the Urabe's theorem. Hence the 2π -periodic solution u of the equation $-u'' = f(t, u)$ is $u = V + W$, where W is obtained by a fixed point iteration procedure for $P_m + H(I - P_m)N$ and V is obtained by the Newton's algorithm for the system $F(c) = 0$ (every step requires the iterations for W).

We consider the following error sources:

- a) The computation of the Fourier coefficients (cf. [5]) of $w^s = H(I - P_m)N(v + w^{s-1})$.

Theorem 7. *If $g(t)$ is p times continuously differentiable, 2π -periodic and his Fourier series is*

$$\frac{a_0}{2} + \sum_{k=1}^{\infty} (a_k \cos kt + b_k \sin kt)$$

then the Fourier coefficients may be approximated by

$$a_k \approx \frac{1}{N} \sum_{i=1}^{2N} g(t_i) \cos nt_i \quad b_k \approx \frac{1}{N} \sum_{i=1}^{2N} g(t_i) \sin nt_i$$

where $t_i = (2i - 1)\pi/(2N)$, $i = 1, \dots, 2N$ and $k = 1, \dots, N - 1$ and the approximation error is

$$2\sigma_p(N - 1) \left[\frac{1}{2\pi} \int_0^{2\pi} g^{(p)}(t)^2 dt \right]^{1/2}$$

where

$$\sigma_p(N - 1) = \sqrt{2} \left[\frac{1}{N^{2p}} + \frac{1}{(N + 1)^{2p}} + \dots \right]^{1/2} < \sqrt{\frac{2}{2p - 1}} (N - 1)^{-p+1/2}$$

b) The truncation of the Fourier series at rank $N - 1$ (cf. [5]). We have

$$\left| g(t) - \frac{a_0}{2} - \sum_{k=1}^{N-1} (a_k \cos kt + b_k \sin kt) \right| \leq \sigma_p(N - 1) \left[\frac{1}{2\pi} \int_0^{2\pi} g^{(p)}(t)^2 dt \right]^{\frac{1}{2}}$$

Consequently, if w^s is approximated by \tilde{w}^s we have

$$\begin{aligned} \|w^s - \tilde{w}^s\| &\leq 2\sqrt{N - m} \sigma_p(N - 1) \left[\frac{1}{2\pi} \int_0^{2\pi} N (v + w^{s-1})^{(p)}(t)^2 dt \right]^{\frac{1}{2}} (\sigma(m) - \sigma(N)) + \\ &\quad + \sigma_p(N - 1) \left[\frac{1}{2\pi} \int_0^{2\pi} N (v + w^{s-1})^{(p)}(t)^2 dt \right]^{\frac{1}{2}} \end{aligned}$$

where

$$\sigma(m) = \left(\sum_{i=m+1}^{\infty} \frac{1}{i^2} \right)^{\frac{1}{2}}$$

At every step we have an error $\varepsilon_s \leq \mathcal{K} (N_s - 1)^{-p+1/2}$, where

$$\mathcal{K} = \sqrt{\frac{2}{2p - 1}} (1 + 2\sqrt{N - m}) \sigma(m) \max_{s \leq S} \left[\frac{1}{2\pi} \int_0^{2\pi} N (v + w^{s-1})^{(p)}(t)^2 dt \right]^{\frac{1}{2}}$$

if $N_s \leq N$ for $s = 1, 2, \dots, S$.

The whole error for S iterations is

$$\|W - \tilde{w}^{s+1}\| \leq \frac{\theta^{s+1} b}{1 - \theta} + \sum_{i=0}^S \frac{\theta^i}{\theta^i} \frac{\mathcal{K}}{(N_i - 1)^{p-1/2}} \equiv \varepsilon_0$$

for a computational effort proportional to $2(N_0 + \dots + N_S)$.

Our problem is now to minimize this effort for a given error ε_0 . Let $S \in \mathbb{N}$.

We have to minimize $N_0 + \dots + N_S$ if

$$\sum_{i=0}^S \frac{1}{\theta^i (N_i - 1)^{p-1/2}} = \frac{\varepsilon_0}{\theta^S} - \frac{b\theta}{1 - \theta} \equiv A_S$$

By the Lagrange multipliers rule, let

$$L = N_0 + \dots + N_S + \lambda \left(\sum_{i=0}^S \frac{1}{\theta^i (N_i - 1)^{p-1/2}} - A_S \right)$$

We have the system

$$1 - \frac{\lambda (p - \frac{1}{2})}{\theta^i (N_i - 1)^{p+1/2}} = 0 \text{ for } i = 0, 1, \dots, S$$

$$\sum_{i=0}^S \frac{1}{\theta^i (N_i - 1)^{p-1/2}} = A_S$$

from where

$$N_i = 1 + \frac{\left(\theta^{-\frac{2(S+1)}{2p+1}} - 1 \right)^{\frac{2}{2p-1}}}{A_S^{\frac{2}{2p-1}} \theta^{\frac{2}{2p+1}} \left(\theta^{-\frac{2}{2p+1}} - 1 \right)^{\frac{2}{2p+1}}}$$

for $i = 0, 1, \dots, S$. Now we can choose S for which the computing effort is minimum.

As an example, let us consider the equation (cf. [5])

$$u'' = \sin t - u^3(t)$$

For $m = 1, p = 2, \theta = 0.4, N_0 = 4, N_1 = 4, N_2 = 5, N_3 = 7, N_4 = 10, N_5 = 14, N_6 = 20$ and at every step the fixed point W was obtained by 64 evaluations of $Nu \equiv \sin u - u^3$ (instead of 120 evaluations if at every step we choose $N = 20$, for the same precision).

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