

ON THE GOURSAT PROBLEM FOR HYPERBOLIC FUNCTIONAL-DIFFERENTIAL EQUATIONS

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It is known that in many problems of nonlinear fields theory, plasma physics and etc. (cf. [1]) arise hyperbolic functional-differential equations with so-called 'distributed' deviations (cf. [2]). The main purpose of the present paper is to formulate conditions under which there exist solutions of the Goursat problem, characteristic of functional-differential equations with 'concentrated' deviations (particular case of distributed deviations), using the fixed point theorems, proved by Angelov [3].

Typical in this respect is the following simple example, where the discontinuity of the initial function generates the discontinuity of the solution:

$$\begin{cases} u_{xy}(x, y) = k(x, y)u_{xy}(x-1, y-1), & (x, y) \in \mathbb{R}_+^2 = \{(x, y) : x > 0, y > 0\} \\ u(x, y) = \varphi(x, y), & (x, y) \in A_0 \cup B_0, \end{cases} \quad (1)$$

where

$$u_{xy} = \frac{\partial^2 u}{\partial x \partial y}; \quad A_0 = \{(x, y) : x \geq -1, -1 \leq y \leq 0\},$$

$$B_0 = \{(x, y) : -1 \leq x \leq 0, y \geq -1\};$$

$$\varphi(x, y) = \begin{cases} 1, & (x, y) \in \mathbb{R}_+^x \cup \mathbb{R}_+^y, \\ \mathbb{R}_+^x = \{(x, y) : x \geq 0, y = 0\}, \mathbb{R}_+^y = \{(x, y) : x = 0, y \geq 0\} \\ 0, & (x, y) \in A_0 \cup B_0 \setminus (\mathbb{R}_+^x \cup \mathbb{R}_+^y) \end{cases}$$

$$k(x, y) = 1 - \frac{1}{1+n}, \quad (x, y) \in A_n \cup B_n \quad (n = 1, 2, \dots),$$

$$A_n = \{(x, y) : x \geq n-1, n-1 \leq y \leq n\}, \quad B_n = \{(x, y) : n-1 \leq x \leq n, y \geq n-1\}.$$

Integrating the above equation we have

$$u(x, y) - k(x, y)u(x-1, y-1) = C_1(x) + C_2(y).$$

Then the conditions

$$u(0, 0) - k(0, 0)u(-1, -1) = C_1(0) + C_2(0),$$

$$u(x, 0) - k(x, 0)u(x-1, -1) = C_1(x) + C_2(0),$$

$$u(0, y) - k(0, y)u(-1, y-1) = C_1(0) + C_2(y)$$

imply $C_1(x) + C_2(y) = 1$, so that we obtain the problem

$$u(x, y) = \begin{cases} k(x, y)u(x-1, y-1) + 1, & (x, y) \in \mathbb{R}_+^2 \\ \varphi(x, y), & (x, y) \in A_0 \cup B_0 \end{cases}$$

It is quite obvious that when $(x, y) \in A_n \cup B_n$ then $(x-1, y-1) \in A_{n-1} \cup B_{n-1}$ and we can construct immediately the following solution

$$u(x, y) = \begin{cases} 0, & (x, y) \in (A_0 \cup B_0) \setminus (\mathbb{R}_+^x \cup \mathbb{R}_+^y) \\ 1, & (x, y) \in (A_1 \cup B_1) \setminus (\mathbb{R}_+^{x+1} \cup \mathbb{R}_+^{y+1}) \\ (1 - \frac{1}{3}) + 1, & (x, y) \in (A_2 \cup B_2) \setminus (\mathbb{R}_+^{x+2} \cup \mathbb{R}_+^{y+2}) \\ \dots \\ (1 - \frac{1}{3})(1 - \frac{1}{4}) \dots (1 - \frac{1}{n+1}) + (1 - \frac{1}{4})(1 - \frac{1}{5}) \dots (1 - \frac{1}{n+1}) + \dots + \\ \quad + (1 - \frac{1}{n+1}) + 1 = \frac{n(n+3)}{2(n+1)}, & (x, y) \in (A_n \cup B_n) \setminus (\mathbb{R}_+^{x+n} \cup \mathbb{R}_+^{y+n}) \\ \dots \end{cases}$$

where $\mathbb{R}_+^{x+n} = \{(x, y) : x \geq n, y = n\}$, $\mathbb{R}_+^{y+n} = \{(x, y) : x = n, y \geq n\}$, $n = 0, 1, 2, \dots$

The fixed point technique for operators in metric spaces has been very well developed (cf. [4]), but the above example shows that the hyperbolic functional-differential equations of neutral type (following the terminology introduced in [5]) possesses solutions with locally essentially bounded mixed derivative u_{xy} . (We note the known results [6]-[8], where only continuous solutions have been obtained with restrictions on the deviations of retarded type.) Moreover the example shows:

1. the Goursat problem allows L_{loc}^∞ -solutions so that it cannot formulate as an operator equation in Banach or metric space.

2. the operator defined by the right-hand side (even in the linear case) will be not a global contraction because of $esssup\{k(x, y) : x \geq 0, y \geq 0\} = 1$.

That is why, we shall use the fixed point theorems from [3].

Let X be a Hausdorff sequentially complete uniform space with uniformity defined by a saturated family of pseudometrics $\{\rho_\alpha(x, y)\}_{\alpha \in \mathcal{A}}$, \mathcal{A} being an index set.

Let $\Phi = \{\Phi_\alpha(t) : \alpha \in \mathcal{A}\}$ be a family of functions $\Phi_\alpha(t) : [0, \infty) \rightarrow [0, \infty)$ with the properties

- 1) $\Phi_\alpha(t)$ is monotone non-decreasing and continuous from the right on $[0, \infty)$;
- 2) $\Phi_\alpha(t) < t, \forall t > 0$,

and $j : \mathcal{A} \rightarrow \mathcal{A}$ is a mapping on the index set \mathcal{A} into itself, where $j^0(\alpha) = \alpha$, $j^k(\alpha) = j(j^{k-1}(\alpha))$, $k \in \mathbb{N}$.

Definition. The map $T : Y \rightarrow Y$ is said to be Φ -contraction on Y if

$$\rho_\alpha(Tx, Ty) \leq \Phi_\alpha(\rho_{j(\alpha)}(x, y))$$

for every $x, y \in Y$ and $\alpha \in \mathcal{A}$, $Y \subset X$.

Theorem 1. (theorem 2 from [3]) *Let us suppose*

1. *the operator $T : X \rightarrow X$ is a Φ -contraction;*
2. *for each $\alpha \in \mathcal{A}$ there exists a Φ -function $\bar{\Phi}_\alpha(t)$ such that*

$$\sup\{\Phi_{j^k(\alpha)}(t) : k = 0, 1, 2, \dots\} \leq \bar{\Phi}_\alpha(t)$$

and $\bar{\Phi}_\alpha(t)/t$ is non-decreasing;

3. *there exists an element $x_0 \in X$ such that $\rho_{j^k(\alpha)}(x_0, Tx_0) \leq p(\alpha) < \infty$ ($k = 0, 1, 2, \dots$).*

Then T has at least one fixed point in X .

Theorem 2. (theorem 3 from [3]) *If, in addition, we suppose that*

4. *the sequence $\{\rho_{j^k(\alpha)}(x, y)\}_{k=0}^\infty$ is bounded for each $\alpha \in \mathcal{A}$ and $x, y \in X$,*
i.e.

$$\rho_{j^k(\alpha)}(x, y) \leq q(x, y, \alpha) < \infty \quad (k = 0, 1, 2, \dots).$$

Then the fixed point of T is unique.

Consider the general Goursat problem for hyperbolic functional-differential equation:

$$\begin{aligned} u_{xy}(x, y) &= F(x, y, u(\Delta, \tau), u_x(\alpha, \beta), u_y(\theta, \kappa), u_{xy}(\mu, \nu)), \quad (x, y) \in \mathbb{R}_+^2 \\ u(x, y) &= \psi(x, y), \quad u_x(x, y) = \psi_x(x, y), \quad u_y(x, y) = \psi_y(x, y), \\ u_{xy}(x, y) &= \psi_{xy}(x, y), \quad (x, y) \in \mathbb{R}^2 \setminus \mathbb{R}_+^2, \end{aligned} \quad (2)$$

where $F(x, y, z_1, z_2, z_3, z_4)$, $\Delta = \Delta(x, y)$, $\tau = \tau(x, y)$, $\alpha = \alpha(x, y)$, $\beta = \beta(x, y)$, $\theta = \theta(x, y)$, $\kappa = \kappa(x, y)$, $\mu = \mu(x, y)$, $\nu = \nu(x, y)$ and $\psi(x, y)$ are given functions.

We set

$$\begin{aligned} v(x, y) &= u_{xy}(x, y), \quad \text{when } (x, y) \in \mathbb{R}_+^2, \\ \varphi(x, y) &= \psi_{xy}(x, y), \quad \text{when } (x, y) \in \mathbb{R}^2 \setminus \mathbb{R}_+^2 \end{aligned}$$

and after standard calculations, we obtain

$$\begin{aligned} u(x, y) &= \varphi_0(x, y) + \int_0^x \int_0^y v(\xi, \eta) d\eta d\xi, \\ u_x(x, y) &= \varphi_1(x) + \int_0^y v(x, \eta) d\eta, \\ u_y(x, y) &= \varphi_2(y) + \int_0^x v(\xi, y) d\xi, \end{aligned}$$

where

$$\begin{aligned} \varphi_0(x, y) &= \psi(0, y) + \psi(x, 0) - \psi(0, 0), \\ \varphi_1(x) &= \psi_x(x, 0), \quad \varphi_2(y) = \psi_y(0, y), \end{aligned}$$

so that the problem (2) corresponds the following problem

$$v(x, y) = \begin{cases} F(x, y, \bar{\varphi}_0 + \int_0^\Delta \int_0^\tau v(\xi, \eta) d\eta d\xi, \bar{\varphi}_1 + \int_0^\beta v(\alpha, \eta) d\eta, \bar{\varphi}_2 + \\ \quad + \int_0^\theta v(\xi, \kappa) d\xi, v(\mu, \nu)), \quad (x, y) \in \mathbb{R}_+^2 \\ \varphi(x, y), \quad (x, y) \in \mathbb{R}^2 \setminus \mathbb{R}_+^2, \end{cases} \quad (3)$$

where $\bar{\varphi}_0 = \varphi_0(\Delta(x, y), \tau(x, y))$, $\bar{\varphi}_1 = \varphi_1(\alpha(x, y))$, $\bar{\varphi}_2 = \varphi_2(\kappa(x, y))$.

Definition. The function $u(x, y)$ is said to be a solution (in generalized sense) of problem (2) if the function $v(x, y)$ is a solution of problem (3).

In what follows, we look for a solution of (3), belonging to L_{loc}^∞ .

We say that the function $G : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ has the property (M) if inverse image of every set with null measure is measurable.

Let us suppose:

(A1) ψ is absolutely continuous;

$\psi(x, 0), \psi(0, y), \psi_x(x, 0), \psi_y(0, y)$ are continuous and $\varphi = \psi_{xy} \in L_{loc}^\infty(\mathbb{R}^2 \setminus \mathbb{R}_+^2)$.

(A2) The functions $\Delta, \tau, \alpha, \beta, \theta, \kappa, \mu, \nu : \mathbb{R}_+^2 \rightarrow \mathbb{R}$ are measurable, have the property (M) (without Δ and τ) and map bounded sets into bounded sets.

(A3) $\forall (x, y) \in \mathbb{R}_+^2$ for which $(\Delta(x, y), \tau(x, y)) \in \mathbb{R}_+^2$ (or $(\alpha(x, y), \beta(x, y)) \in \mathbb{R}_+^2$, or $(\theta(x, y), \kappa(x, y)) \in \mathbb{R}_+^2$ is fulfilled $\Delta(x, y) + \tau(x, y) \leq x + y$ (respectively $\alpha(x, y) + \beta(x, y) \leq x + y$, or $\theta(x, y) + \kappa(x, y) \leq x + y$);

$\exists \delta_0 > 0$ such that $\forall (x, y) \in \mathbb{R}_+^2 : (\mu(x, y), \nu(x, y)) \in \mathbb{R}_+^2$ is fulfilled $\mu(x, y) + \nu(x, y) \leq x + y - \delta_0$.

(A4) The function $F(x, y, z_1, z_2, z_3, z_4) : \mathbb{R}_+^2 \times \mathbb{R}^4 \rightarrow \mathbb{R}$ satisfies the Caratheodory condition (measurable in x and y and continuous in z_1, \dots, z_4) and the conditions:

$$|F(x, y, z_1, z_2, z_3, z_4)| \leq \Omega_1(x, y, |z_1|, |z_2|, |z_3|, |z_4|)$$

$$\begin{aligned} & |F(x, y, z_1, z_2, z_3, z_4) - F(x, y, \bar{z}_1, \bar{z}_2, \bar{z}_3, \bar{z}_4)| \leq \\ & \leq \Omega_2(x, y, |z_1 - \bar{z}_1|, |z_2 - \bar{z}_2|, |z_3 - \bar{z}_3|, |z_4 - \bar{z}_4|), \end{aligned}$$

where the functions $\Omega_{1,2}(x, y, t_1, \dots, t_4) : \mathbb{R}_+^2 \times \overline{\mathbb{R}}_+^4 \rightarrow [0, \infty)$ ($\overline{\mathbb{R}}_+^n = [0, \infty) \times \dots \times [0, \infty)$ - n times) satisfy the Caratheodory condition, $\Omega_1(\cdot, \cdot, t_1, \dots, t_4) \in L_{loc}^\infty(\mathbb{R}_+^2)$, $\Omega_2(x, y, t_1, \dots, t_4)$ is non-decreasing in t_1, \dots, t_4 and

$\exists \omega \in L^\infty(\mathbb{R}_+^2)$ such that $\forall t \geq 0$ $\Omega_2(\cdot, \cdot, t, t, t, t) \leq t\omega(\cdot, \cdot)$ a.e. in \mathbb{R}_+^2 .

Let \mathcal{A} be the set of all compact sets $K \subset \mathbb{R}^2$. Denote by $K_+ = K \cap \mathbb{R}_+^2$, we define the map $j : \mathcal{A} \rightarrow \mathcal{A}$:

$$j(K) = \begin{cases} K, & K_+ = \emptyset \\ K_{\Delta\tau} \cup K_{\alpha\beta} \cup K_{\theta\kappa} \cup K_{\mu\nu}, & K_+ \neq \emptyset \end{cases}$$

where $K_{\Delta\tau} = K_\Delta \times K_\tau$, $K_{\alpha\beta} = K_\alpha \times K_\beta$, $K_{\theta\kappa} = K_\theta \times K_\kappa$,

$$K_{\mu\nu} = \overline{\{(\mu(x, y), \nu(x, y)) : (x, y) \in K\}}, \quad (\overline{A} \stackrel{def}{=} cl A),$$

$$K_{\Delta} = \begin{cases} [\Delta_{inf}, \Delta_{sup}], & \Delta_{inf} < 0 < \Delta_{sup} \\ [0, \Delta_{sup}], & \Delta_{inf} \geq 0 \\ [\Delta_{inf}, 0], & \Delta_{sup} \leq 0 \end{cases}$$

$$K_{\tau} = \begin{cases} [\tau_{inf}, \tau_{sup}], & \tau_{inf} < 0 < \tau_{sup} \\ [0, \tau_{sup}], & \tau_{inf} \geq 0 \\ [\tau_{inf}, 0], & \tau_{sup} \leq 0 \end{cases}$$

$$K_{\beta} = \begin{cases} [\beta_{inf}, \beta_{sup}], & \beta_{inf} < 0 < \beta_{sup} \\ [0, \beta_{sup}], & \beta_{inf} \geq 0 \\ [\beta_{inf}, 0], & \beta_{sup} \leq 0 \end{cases}$$

$$K_{\theta} = \begin{cases} [\theta_{inf}, \theta_{sup}], & \theta_{inf} < 0 < \theta_{sup} \\ [0, \theta_{sup}], & \theta_{inf} \geq 0 \\ [\theta_{inf}, 0], & \theta_{sup} \leq 0 \end{cases}$$

$$K_{\alpha} = \overline{\alpha(K)}, \quad K_{\kappa} = \overline{\kappa(K)}$$

$$(\Delta_{inf} = \inf\{\Delta(x, y) : (x, y) \in K_{+}\}, \dots, \theta_{sup} = \sup\{\theta(x, y) : (x, y) \in K_{+}\}).$$

It is obvious that $j(K)$ is compact set and $j^l(K)$ can be defined inductively: $j^l(K) = j(j^{l-1}(K))$ for all $l \in \mathbb{N}$.

Now we assume:

$$(A5) \quad \forall K \in \mathcal{A} \exists \widehat{K} \in \mathcal{A} : j^l(K) \subset \widehat{K} \quad \forall l = 0, 1, 2, \dots$$

We prove the following existence-uniqueness result:

Theorem 3. *If conditions (A1)-(A5) hold true, then there exists a unique solution $v(x, y) \in L_{loc}^{\infty}(\mathbb{R}^2)$ of problem (3).*

Proof. Let X be the uniform sequentially complete Hausdorff space consisting of all functions, belonging to $L_{loc}^{\infty}(\mathbb{R}^2)$, which equal $\varphi(x, y)$ for a.e. $(x, y) \in \mathbb{R}^2 \setminus \mathbb{R}_+^2$, with a saturated family $P = \{\rho_K : K \in \mathcal{A}\}$ of pseudometrics

$$\rho_K(f, g) = \text{esssup}\{e^{-\lambda(|x|+|y|)}|f(x, y) - g(x, y)| : (x, y) \in K\},$$

where K runs over all compact subsets of \mathbb{R}^2 (with some $\lambda > 0$).

The operator $T : X \rightarrow X$ is defined by the formula:

$$T(f)(x, y) = \begin{cases} F(x, y, \bar{\varphi}_0 + \int_0^\Delta \int_0^\tau f(\xi, \eta) d\eta d\xi, \bar{\varphi}_1 + \int_0^\beta f(\alpha, \eta) d\eta, \bar{\varphi}_2 + \\ \quad + \int_0^\theta f(\xi, \kappa) d\xi, f(\mu, \nu)), (x, y) \in \mathbb{R}_+^2 \\ \varphi(x, y), (x, y) \in \mathbb{R}^2 \setminus \mathbb{R}_+^2, \end{cases}$$

The measurability of $T(f)(x, y)$ follows from the fact that $\alpha, \beta, \theta, \kappa, \mu, \nu$ have the property (M).

$T(f) \in L_{loc}^\infty(\mathbb{R}^2)$ because of conditions A1, A4. Consequently $T(f) \in X$.

Let $K \subset \mathbb{R}^2$ be any fixed compact set. Of $K_+ = \emptyset$ then $T(f) - T(g) = 0$ for all $f, g \in X$ a.e. in K . Let $K_+ \neq \emptyset$. For a.e. $(x, y) \in K \cap (\mathbb{R}^2 \setminus \mathbb{R}_+^2)$ we have $T(f) - T(g) = 0$.

For a.e. $(x, y) \in K_+$ we obtain (by means of (A4)):

$$\begin{aligned} & |T(f)(x, y) - T(g)(x, y)| \leq \\ & \leq \Omega_2(x, y, |\int_0^\Delta \int_0^\tau (f(\xi, \eta) - g(\xi, \eta)) d\eta d\xi|, |\int_0^\beta (f(\alpha, \eta) - g(\alpha, \eta)) d\eta|, \\ & \quad |\int_0^\theta (f(\xi, \kappa) - g(\xi, \kappa)) d\xi|, |f(\mu, \nu) - g(\mu, \nu)|) \end{aligned}$$

If $(\Delta(x, y), \tau(x, y)) \notin \mathbb{R}_+^2$ then

$$\int_0^\Delta \int_0^\tau (f(\xi, \eta) - g(\xi, \eta)) d\eta d\xi = 0$$

and respectively if $(\alpha(x, y), \beta(x, y)) \notin \mathbb{R}_+^2$ then

$$\int_0^\beta (f(\alpha, \eta) - g(\alpha, \eta)) d\eta = 0,$$

if $(\theta(x, y), \kappa(x, y)) \notin \mathbb{R}_+^2$ then

$$\int_0^\theta (f(\xi, \kappa) - g(\xi, \kappa)) d\xi = 0,$$

if $(\mu(x, y), \nu(x, y)) \notin \mathbb{R}_+^2$ then $f(\mu, \nu) - g(\mu, \nu) = 0$.

For positive values of $\Delta(x, y), \tau(x, y); \alpha(x, y), \beta(x, y); \theta(x, y), \kappa(x, y); \mu(x, y), \nu(x, y)$ we obtain as follows:

$$|\int_0^\Delta \int_0^\tau (f(\xi, \eta) - g(\xi, \eta)) d\eta d\xi| \leq \int_0^\Delta \int_0^\tau |f(\xi, \eta) - g(\xi, \eta)| d\eta d\xi \leq$$

$$\begin{aligned}
&\leq \text{esssup}\{e^{-\lambda(\xi+\eta)}|f(\xi, \eta) - g(\xi, \eta)| : 0 \leq \xi \leq \Delta_{sup}, 0 \leq \eta \leq \tau_{sup}\} \int_0^\Delta \int_0^\tau e^{\lambda(\xi+\eta)} d\eta d\xi = \\
&= \lambda^{-2} \rho_{K_{\Delta\tau}}(f, g)(e^{\lambda\Delta} - 1)(e^{\lambda\tau} - 1) \leq \lambda^{-2} e^{\lambda(\Delta+\tau)} \rho_{K_{\Delta\tau}} \leq \lambda^{-2} e^{\lambda(x+y)} \rho_{K_{\Delta\tau}}(f, g) \text{ (cf. (A3))}. \\
&\quad \left| \int_0^\beta (f(\alpha, \eta) - g(\alpha, \eta)) d\eta \right| \leq \int_0^\beta |f(\alpha, \eta) - g(\alpha, \eta)| d\eta \leq \\
&\quad \leq \text{esssup}\{e^{-\lambda(\alpha+\eta)}|f(\alpha, \eta) - g(\alpha, \eta)| : 0 \leq \eta \leq \beta_{sup}\} e^{\lambda\alpha} \int_0^\beta e^{\lambda\eta} d\eta \leq \\
&\leq \lambda^{-1} \rho_{K_{\alpha\beta}}(f, g) e^{\lambda\alpha} (e^{\lambda\beta} - 1) \leq \lambda^{-1} e^{\lambda(\alpha+\beta)} \rho_{K_{\alpha\beta}}(f, g) \leq \lambda^{-1} e^{\lambda(x+y)} \rho_{K_{\alpha\beta}}(f, g) \text{ (cf. (A3))}.
\end{aligned}$$

In the same way we prove (by means of (A3)) that

$$\begin{aligned}
&\left| \int_0^\theta (f(\xi, \kappa) - g(\xi, \kappa)) d\xi \right| \leq \lambda^{-1} e^{\lambda(x+y)} \rho_{K_{\theta\kappa}}(f, g). \\
&|f(\mu, \nu) - g(\mu, \nu)| \leq e^{\lambda(\mu+\nu)} \text{esssup}\{e^{-\lambda(p+q)}|f(p, q) - g(p, q)| : (p, q) \leq K_{\mu\nu}\} \leq \\
&\leq e^{\lambda(x+y-\delta_0)} \rho_{K_{\mu\nu}}(f, g) \leq \lambda^{-\delta_0} e^{\lambda(x+y)} \rho_{K_{\mu\nu}}(f, g) \text{ (cf. (A3))}.
\end{aligned}$$

Let $\lambda > 1$. Chosing γ so that

$$\lambda^{-\gamma} = \max\{\lambda^{-1}, \lambda^{-\delta_0}\} = \begin{cases} \lambda^{-1}, & \delta_0 \geq 1 \\ \lambda^{-\delta_0}, & 0 < \delta_0 \leq 1 \end{cases}$$

we obtain (since $\Omega_2(x, y, t_1, \dots, t_4)$ is non-decreasing in t_1, \dots, t_4)

$$\begin{aligned}
&|T(f)(x, y) - T(g)(x, y)| \leq \\
&\leq \Omega_2(x, y, \lambda^{-\gamma} e^{\lambda(x+y)} \rho_{j(K)}(f, g), \lambda^{-\gamma} e^{\lambda(x+y)} \rho_{j(K)}(f, g), \\
&\quad \lambda^{-\gamma} e^{\lambda(x+y)} \rho_{j(K)}(f, g), \lambda^{-\gamma} e^{\lambda(x+y)} \rho_{j(K)}(f, g)) \leq \\
&\leq \lambda^{-\gamma} e^{\lambda(x+y)} \rho_{j(K)}(f, g) \omega(x, y) \text{ (cf. (A4))}.
\end{aligned}$$

Define (for $t \geq 0$)

$$\Phi_K(t) = \begin{cases} 0, & \text{if } K_+ = \emptyset \\ t\lambda^{-\gamma} \|\omega\|_{L^\infty(K_+)}, & \text{if } K_+ \neq \emptyset \end{cases}$$

We can find and fix λ so that $\lambda^\gamma > \|\omega\|_{L^\infty(\mathbb{R}_+^2)}$. Consequently $\Phi_K(t) < t$ $\forall t > 0$, $\forall K \in \mathcal{A}$ and $\Phi_K(t)$ is continuous non-decreasing in $[0, \infty)$. On the other hand

$$\rho_K(T(f), T(g)) = \rho_{\overline{K}_+}(T(f), T(g)) \leq \Phi_K(\rho_{j(K)}(f, g)),$$

i.e. $T : X \rightarrow X$ is a Φ -contraction.

$\forall K \in \mathcal{A}$ we set $\overline{\Phi}_K = \Phi_{\widehat{K}}$ (recall that (A5) assures an existence of such a \widehat{K} that $j^l(K) \subset \widehat{K}$ ($l = 0, 1, 2, \dots$)) and so $\sup\{\Phi_{j^l(K)}(t) : l = 0, 1, 2, \dots\} \leq \overline{\Phi}_K(t)$, $\frac{\overline{\Phi}_K(t)}{t} = \text{const} \Rightarrow$ non-decreasing.

Hence condition 1, 2 of theorem 1 is fulfilled.

We choose the element $f_0 \in X$:

$$f_0(x, y) = \begin{cases} 0, & \text{a.e. on } \mathbb{R}_+^2 \\ \varphi(x, y), & (x, y) \in \mathbb{R}^2 \setminus \mathbb{R}_+^2. \end{cases}$$

Then for any integer $l \geq 0$ we have

$$\begin{aligned} \rho_{j^l(K)}(f_0, T(f_0)) &\leq \rho_{\widehat{K}}(f_0, T(f_0)) = \rho_{\overline{\widehat{K}_+}}(f_0, T(f_0)) = \\ &= \text{esssup}\{e^{-\lambda(x+y)}|F(x, y, \overline{\varphi}_0, \overline{\varphi}_1, \overline{\varphi}_2, 0)| : (x, y) \in \overline{\widehat{K}_+}\} < \infty \end{aligned}$$

(i.e. condition 3 of theorem 1 is fulfilled).

Besides $\rho_{j^l(K)}(f, g) \leq \rho_{\overline{\widehat{K}_+}}(f, g)$ for arbitrary $f, g \in X$, i.e. condition 4 of theorem 2 is also fulfilled.

All conditions of theorems 1 and 2 are satisfied. Therefore the problem (3) has a unique solution $v \in L_{loc}^\infty(\mathbb{R}^2)$.

We are going to formulate conditions for the existence and uniqueness of a solution of (3) belonging to $L_{loc}^p(\mathbb{R}^2)$ for some $p \in (1, \infty)$:

(A1') The initial function ψ is absolutely continuous;

$\psi(x, 0), \psi(0, y), \psi_x(x, 0), \psi_y(0, y)$ are continuous and $\varphi = \psi_{xy} \in L_{loc}^p(\mathbb{R}^2 \setminus \mathbb{R}_+^2)$.

(A4') The function $F(x, y, z_1, z_2, z_3, z_4) : \mathbb{R}_+^2 \times \mathbb{R}^4 \rightarrow \mathbb{R}$ satisfies the Caratheodory condition (measurable in x and y and continuous in z_1, \dots, z_4) and the conditions:

$$|F(x, y, z_1, z_2, z_3, z_4)| \leq a(x, y) + b(|z_1| + |z_2| + |z_3| + |z_4|)$$

$$|F(x, y, z_1, z_2, z_3, z_4) - F(x, y, \bar{z}_1, \bar{z}_2, \bar{z}_3, \bar{z}_4)| \leq$$

$$\leq \omega_1(x, y)|z_1 - \bar{z}_1| + \omega_2|z_2 - \bar{z}_2| + \omega_3|z_3 - \bar{z}_3| + \omega_4|z_4 - \bar{z}_4|,$$

where $a(\cdot, \cdot) \in L_{loc}^p(\mathbb{R}_+^2)$, $b = \text{const} \geq 0$, $\omega_1(\cdot, \cdot) \in L^p(\mathbb{R}_+^2)$, $\omega_{2,3}(\cdot) \in L^p(\mathbb{R}_+^1)$,

$\omega_4 = \text{const} \geq 0$

(A6) The transformations

$$\left| \begin{array}{l} u = \alpha(x, y) \\ v = y \end{array} \right| \quad \left| \begin{array}{l} u = x \\ v = \kappa(x, y) \end{array} \right| \quad \left| \begin{array}{l} u = \mu(x, y) \\ v = \nu(x, y) \end{array} \right|$$

are admissible, sufficiently smooth and $\alpha_u^*, \kappa_v^*, \frac{D(\mu^*, \nu^*)}{D(u, v)} \in L^\infty(\mathbb{R}_+^2)$, where

$$(\alpha^*(\alpha(x, y), y), y) = (x, y), \quad (x, \kappa^*(x, \kappa(x, y))) = (x, y),$$

$$(\mu^*(\mu(x, y), \nu(x, y)), \nu^*(\mu(x, y), \nu(x, y))) = (x, y).$$

Theorem 4. *If conditions (A1'), (A2), (A3), (A4'), (A5), (A6) hold true, then there exists a unique solution $v(x, y) \in L_{loc}^p(\mathbb{R}^2)$ of problem (3).*

Proof. Let X be the space consisting of all functions, belonging to $L_{loc}^p(\mathbb{R}^2)$, which equal $\varphi(x, y)$ a.e. $(x, y) \in \mathbb{R}^2 \setminus \mathbb{R}_+^2$, with a saturated family P of pseudometrics

$$\rho_K(f, g) = \left(\int_K \int e^{-\lambda(|x|+|y|)} |f(x, y) - g(x, y)|^p dx dy \right)^{\frac{1}{p}} \quad (K \in \mathcal{A}),$$

where \mathcal{A} is the family of all compact sets in \mathbb{R}^2 , $\lambda > 0$.

The map $j : \mathcal{A} \rightarrow \mathcal{A}$ and the operator $T : X \rightarrow X$ are defined as in the proof of theorem 3.

For any $K \in \mathcal{A}$, $f, g \in X$ we have $T(f)(x, y) - T(g)(x, y) = 0$, for a.e. $(x, y) \in K \setminus K_+$;

If $(x, y) \in K_+ \neq \emptyset$, then

$$\begin{aligned} & |T(f)(x, y) - T(g)(x, y)|^p \leq \\ & \leq \left(\omega_1(x, y) \left| \int_0^\Delta \int_0^\tau (f(\xi, \eta) - g(\xi, \eta)) d\eta d\xi \right| + \omega_2(y) \left| \int_0^\beta (f(\alpha, \eta) - g(\alpha, \eta)) d\eta \right| + \right. \\ & \quad \left. + \omega_3(x) \left| \int_0^\theta (f(\xi, \kappa) - g(\xi, \kappa)) d\xi \right| + \omega_4 |f(\mu, \nu) - g(\mu, \nu)| \right)^p \leq \\ & \leq 4^{p-1} \left(\omega_1^p(x, y) \left| \int_0^\Delta \int_0^\tau (f(\xi, \eta) - g(\xi, \eta)) d\eta d\xi \right|^p + \omega_2^p(y) \left| \int_0^\beta (f(\alpha, \eta) - g(\alpha, \eta)) d\eta \right|^p + \right. \\ & \quad \left. + \omega_3^p(x) \left| \int_0^\theta (f(\xi, \kappa) - g(\xi, \kappa)) d\xi \right|^p + \omega_4^p |f(\mu, \nu) - g(\mu, \nu)|^p \right). \end{aligned}$$

If $(\Delta, \tau), (\alpha, \beta), (\theta, \kappa), (\mu, \nu) \notin \mathbb{R}_+^2$, then $T(f)(x, y) - T(g)(x, y) = 0$.

If $(\Delta, \tau) \in \mathbb{R}_+^2$, then (with $\frac{1}{p} + \frac{1}{q} = 1$)

$$\begin{aligned}
 & \left| \int_0^\Delta \int_0^\tau (f(\xi, \eta) - g(\xi, \eta)) d\eta d\xi \right|^p \leq \\
 & \leq \left(\int_0^\Delta \int_0^\tau |f(\xi, \eta) - g(\xi, \eta)| d\eta d\xi \right)^p = \\
 & = \left(\int_0^\Delta \int_0^\tau e^{\frac{\lambda}{p}(\xi+\eta-\xi-\eta)} |f(\xi, \eta) - g(\xi, \eta)| d\eta d\xi \right)^p \leq \\
 & \leq \left(\int_0^\Delta \int_0^\tau e^{\frac{\lambda}{p}(\xi+\eta)} d\eta d\xi \right)^{\frac{p}{q}} \int_0^\Delta \int_0^\tau e^{-\lambda(\xi+\eta)} |f(\xi, \eta) - g(\xi, \eta)|^p d\eta d\xi \leq \\
 & \leq \left(\frac{p-1}{\lambda} \right)^{2(p-1)} e^{\lambda(\Delta+\tau)} \rho_{K_{\Delta\tau}}^p(f, g) \leq \\
 & \leq \left(\frac{p-1}{\lambda} \right)^{2(p-1)} e^{\lambda(x+y)} \rho_{K_{\Delta\tau}}^p(f, g) \quad (\text{cf. (A3)}).
 \end{aligned}$$

If $(\alpha, \beta) \in \mathbb{R}_+^2$, then

$$\begin{aligned}
 & \left| \int_0^\beta (f(\alpha, \eta) - g(\alpha, \eta)) d\eta \right|^p \leq \\
 & \leq \left(\int_0^\beta |f(\alpha, \eta) - g(\alpha, \eta)| d\eta \right)^p = \left(\int_0^\beta e^{\frac{\lambda}{p}(\alpha+\eta-\alpha-\eta)} |f(\alpha, \eta) - g(\alpha, \eta)| d\eta \right)^p \leq \\
 & \leq \left(\int_0^\beta e^{\frac{\lambda}{p}(\alpha+\eta)} d\eta \right)^{\frac{p}{q}} \int_0^\beta e^{-\lambda(\alpha+\eta)} |f(\alpha, \eta) - g(\alpha, \eta)|^p d\eta \leq \\
 & \leq \left(\frac{p-1}{\lambda} \right)^{p-1} e^{\lambda(\alpha+\beta)} \int_0^\beta e^{-\lambda(\alpha+\eta)} |f(\alpha, \eta) - g(\alpha, \eta)|^p d\eta \leq \\
 & \leq \left(\frac{p-1}{\lambda} \right)^{p-1} e^{\lambda(x+y)} \int_0^\beta e^{-\lambda(\alpha+\eta)} |f(\alpha, \eta) - g(\alpha, \eta)|^p d\eta \quad (\text{cf. (A3)}).
 \end{aligned}$$

In the same way (by means of (A3)) we obtain: if $(\theta, \kappa) \in \mathbb{R}_+^2$, then

$$\left| \int_0^\theta (f(\xi, \kappa) - g(\xi, \kappa)) d\xi \right|^p \leq \left(\frac{p-1}{\lambda} \right)^{p-1} e^{\lambda(x+y)} \int_0^\theta e^{-\lambda(\xi+\kappa)} |f(\xi, \kappa) - g(\xi, \kappa)|^p d\xi.$$

Hence

$$\int_K \int e^{-\lambda(|x|+|y|)} |T(f)(x, y) - T(g)(x, y)|^p dx dy \leq$$

$$\begin{aligned}
&\leq 4^{p-1} \left(\left(\frac{p-1}{\lambda} \right)^{2(p-1)} \rho_{K_{\Delta r}}^p(f, g) \int_{K_+} \int \omega_1^p(x, y) dx dy + \right. \\
&+ \left(\frac{p-1}{\lambda} \right)^{p-1} \int_{K_+} \int \omega_2^p(y) \int_0^\beta e^{-\lambda(\alpha+\eta)} |f(\alpha, \eta) - g(\alpha, \eta)|^p d\eta dx dy + \\
&+ \left(\frac{p-1}{\lambda} \right)^{p-1} \int_{K_+} \int \omega_3^p(x) \int_0^\theta e^{-\lambda(\xi+\kappa)} |f(\xi, \kappa) - g(\xi, \kappa)|^p d\xi dx dy + \\
&\quad \left. + \omega_4^p e^{-\lambda\delta_0} \int_{K_+} \int e^{-\lambda(\mu+\nu)} |f(\mu, \nu) - g(\mu, \nu)|^p dx dy \right).
\end{aligned}$$

Denote $K_y = \{y : (x, y) \in K_+\}$, $K_x = \{x : (x, y) \in K_+\}$. Consequently

$$\begin{aligned}
&\int_{K_+} \int \omega_2^p(y) \int_0^\beta e^{-\lambda(\alpha+\eta)} |f(\alpha, \eta) - g(\alpha, \eta)|^p d\eta dx dy \leq \\
&\leq \int_{K_y} \omega_2^p(v) \int_{K_\alpha} \int_{K_\beta} |\alpha_u^*(u, v)| e^{-\lambda(u+\eta)} |f(u, \eta) - g(u, \eta)|^p d\eta dudv \leq \\
&\leq \|\alpha_u^*\|_{L^\infty(\mathbb{R}_+^2)} \rho_{K_{\alpha\beta}}^p(f, g) \int_{K_y} \omega_2^p(v) dv
\end{aligned}$$

and similarly

$$\begin{aligned}
&\int_{K_+} \int \omega_3^p(x) \int_0^\theta e^{-\lambda(\xi+\kappa)} |f(\xi, \kappa) - g(\xi, \kappa)|^p d\xi dx dy \leq \\
&\leq \|\kappa_v^*\|_{L^\infty(\mathbb{R}_+^2)} \rho_{K_{\theta\kappa}}^p(f, g) \int_{K_x} \omega_3^p(u) du. \\
&\int_{K_+} \int e^{-\lambda(\mu+\nu)} |f(\mu, \nu) - g(\mu, \nu)|^p dx dy = \\
&= \int_{K_{\mu\nu}} \int \left| \frac{D(\mu^*, \nu^*)}{D(u, v)} \right| e^{-\lambda(u+v)} |f(u, v) - g(u, v)|^p dudv \leq \\
&\leq \left\| \frac{D(\mu^*, \nu^*)}{D(u, v)} \right\|_{L^\infty(\mathbb{R}_+^2)} \rho_{K_{\mu\nu}}^p(f, g).
\end{aligned}$$

Thus we receive the estimate

$$\begin{aligned}
\rho_K^p(T(f), T(g)) &\leq 4^{p-1} \rho_{j(K)}^p(f, g) \left(\left(\frac{p-1}{\lambda} \right)^{2p-2} \|\omega_1\|_{L^p(K_{\Delta r})}^p + \right. \\
&+ \left. \left(\frac{p-1}{\lambda} \right)^{p-1} C_\alpha \|\omega_2\|_{L^p(K_y)}^p + \left(\frac{p-1}{\lambda} \right)^{p-1} C_\kappa \|\omega_3\|_{L^p(K_x)}^p + \lambda^{-\delta_0} C_{\mu\nu} \omega_4^p \right),
\end{aligned}$$

where $C_\alpha = \|\alpha_u^*\|_{L^\infty(\mathbb{R}_+^2)}$, $C_\kappa = \|\kappa_v^*\|_{L^\infty(\mathbb{R}_+^2)}$, $C_{\mu\nu} = \left\| \frac{D(\mu^*, \nu^*)}{D(u, v)} \right\|_{L^\infty(\mathbb{R}_+^2)}$.

Define

$$\Phi_K(t) = \begin{cases} 0, & K_+ = \emptyset \\ t \sqrt{\left(\frac{2p-2}{\lambda}\right)^{2p-2} \|\omega_1\|_{L^p(K_{\Delta\tau})}^p + \left(\frac{4p-4}{\lambda}\right)^{p-1} C_\alpha \|\omega_2\|_{L^p(K_y)}^p + \left(\frac{4p-4}{\lambda}\right)^{p-1} C_\kappa \|\omega_3\|_{L^p(K_x)}^p + \frac{(4\omega_4)^p C_{\mu\nu}}{4\lambda^{\delta_0}}}, & K_+ \neq \emptyset \end{cases}$$

Then $\rho_K(T(f), T(g)) \leq \Phi_K(\rho_j(K)(f, g)) \forall K \in \mathcal{A}, \forall f, g \in X$.

We can find and fix $\lambda > 1$ so that

$$\begin{aligned} & \left(\frac{2p-2}{\lambda}\right)^{2p-2} \|\omega_1\|_{L^p(\mathbb{R}_+^2)}^p + \left(\frac{4p-4}{\lambda}\right)^{p-1} C_\alpha \|\omega_2\|_{L^p(\mathbb{R}_+^1)}^p + \\ & + \left(\frac{4p-4}{\lambda}\right)^{p-1} C_\kappa \|\omega_3\|_{L^p(\mathbb{R}_+^1)}^p + \frac{(4\omega_4)^p C_{\mu\nu}}{4\lambda^{\delta_0}} < 1 \end{aligned}$$

for example

$$\begin{aligned} \lambda > \max\{2^q(p-1)\|\omega_1\|_{L^p(\mathbb{R}_+^2)}^{q/2}, 4^q C_\alpha^{q/p}(p-1)\|\omega_2\|_{L^p(\mathbb{R}_+^1)}^q, \\ 4^q C_\kappa^{q/p}(p-1)\|\omega_3\|_{L^p(\mathbb{R}_+^1)}^q, C_{\mu\nu}^{1/\delta_0}(4\omega_4)^{p/\delta_0}\}. \end{aligned}$$

Consequently $\Phi_K(t) < t$, $\Phi_K(t)/t = \text{const}$ and T is a Φ -contraction.

K_+ is bounded set $\Rightarrow \Delta(K_+), \tau(K_+), \alpha(K_+), \kappa(K_+)$ are bounded sets too,

so (A1') implies $\exists C_K = \text{const} \geq 0$:

$$|F(x, y, \varphi_0(\Delta, \tau), \varphi_1(\alpha), \varphi_2(\kappa), 0)| \leq a(x, y) + bC_K \in L_{loc}^p(\mathbb{R}_+^2) \text{ (cf. (A1'))}.$$

We choose the element $f_0 \in X$:

$$f_0(x, y) = \begin{cases} 0, & \text{a.e. on } \mathbb{R}_+^2 \\ \varphi(x, y), & (x, y) \in \mathbb{R}^2 \setminus \mathbb{R}_+^2. \end{cases}$$

Then

$$T(f_0) = \begin{cases} F(x, y, \varphi_0(\Delta, \tau), \varphi_1(\alpha), \varphi_2(\kappa), 0), & \text{a.e. on } \mathbb{R}_+^2 \\ \varphi(x, y), & (x, y) \in \mathbb{R}^2 \setminus \mathbb{R}_+^2. \end{cases} \Rightarrow T(f_0) \in X$$

and consequently

$$\begin{aligned} \|T(f)\|_{L^p(K)} & \leq \|T(f) - T(f_0)\|_{L^p(K)} + \|T(f_0)\|_{L^p(K)} \leq \\ & \leq \left(\max_{(x,y) \in K} e^{\lambda(|x|+|y|)}\right)^{\frac{1}{p}} \rho_K(T(f), T(f_0)) + \|T(f_0)\|_{L^p(K)} \leq \\ & \leq c(K, \lambda, p) \rho_j(K)(f, f_0) + \|T(f_0)\|_{L^p(K)}, \forall f \in X. \end{aligned}$$



But $\rho_{j(K)}(f, f_0) \leq \|f\|_{L^p(j(K) \cap \mathbb{R}_+^2)} \Rightarrow T(f) \in X$.

Besides the estimates $\rho_{j^l(K)}(f_0, T(f_0)) \leq \rho_{\widehat{K}}(f_0, T(f_0))$, $\rho_{j^l(K)}(f, g) \leq \rho_{\widehat{K}}(f, g)$ for any integer $l \geq 0$, $\forall f, g \in X$ (cf. (A5)) show that conditions 3 of theorem 1 and 4 of theorem 2 are fulfilled. Using once again (A5), we check that condition 2 of theorem 1 is also fulfilled, which completes the proof of theorem 4.

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