

On skew group algebras and symmetric algebras

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Abstract. We identify and define a class of algebras which we call inv-symm algebras and prove that are principally symmetric. Two important examples are given, and we prove that the skew group algebra associated to these algebras remains inv-symm.

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1. Inv-symm algebras

Following [2] we recall the concept of an inverse semigroup and we use basic results without comments. A semigroup (S, \cdot) is *inverse* if for any $s \in S$ there is a unique \widehat{s} (named inverse) such that $s \cdot \widehat{s} \cdot s = s$ and $\widehat{s} \cdot s \cdot \widehat{s} = \widehat{s}$. By [2, 1.1, Theorem 3], if (S, \cdot) is inverse then all idempotents of S commutes and we have $\widehat{\widehat{s}} = s$ and $\widehat{s \cdot t} = \widehat{t} \cdot \widehat{s}$ for any $s \in S$. We denote usually by k a commutative ring and by A a k -algebra. If B is a subset of A with $0 \notin B$, we denote by $B^\#$ the set $B \cup \{0\}$ and by $\text{Idemp}(B)$ the set of all idempotents of B . The following definition is suggested by the ideas from [3] and by methods used to prove that the group algebra is a symmetric algebra.

Definition 1.1. *A k -algebra A is inv-symm if there is a finite k -basis B such that:*

- (1) $(B^\#, \cdot)$ is an inverse semigroup.
- (2) For $t, s \in B$ we have $t \cdot s \neq 0$ if and only if $s \cdot \widehat{s} = \widehat{t} \cdot t$.

Example 1.2. If $A = kG$ is the group algebra over a finite group G then the finite set $B = G$ is a k -basis which satisfies conditions from Definition 1.1. We have in this case $\widehat{s} = s^{-1}$, $t \cdot s \neq 0$ and $s \cdot \widehat{s} = \widehat{t} \cdot t$ for any $t, s \in B$.

Example 1.3. If $A = \text{End}_k(M)$, where M is a kG -lattice (that is a finitely generated, free k -module with a G -stable finite basis X), then $B = \{b_{x,y} \mid x, y \in X\}$ with $b_{x,y} : M \rightarrow M$, $b_{x,y}(z) = x$ if $z = y$, and $b_{x,y}(z) = 0$ if $z \neq y$, satisfies the conditions from 1.1. It requires some computation to verify that $b_{x,y} \circ b_{x_1,y_1} = 0$ if $y \neq x_1$, and $b_{x,y} \circ b_{x_1,y_1} = b_{x,y_1}$ if $y = x_1$. We have that $b_{x,y} \in \text{Idemp}(B)$ if and only if $x = y$.

Remark 1.4. Moreover the above two examples are also G -algebras with G -stable basis. This suggest that we can define a class of symmetric G -algebras and to analyze the skew group algebra in this case.

Lemma 1.5. *Let A be an inv-symm k -algebra with basis B satisfying Definition 1.1 and $t, s \in B$. The following statements are true:*

- a) *For $0 \in B^\sharp$ we have $\widehat{0} = 0$ and $s \in B$ if and only if $\widehat{s} \in B$.*
- b) *For all $s \in B$ we have $s \cdot \widehat{s} \in \text{Idemp}(B)$ and $\widehat{s} \cdot s \in \text{Idemp}(B)$. Particularly $\text{Idemp}(B) \neq \emptyset$.*
- c) *If $t \cdot s \neq 0$ and $t \cdot s \in \text{Idemp}(B)$ then $t = \widehat{s}$.*

Proof. a) For 0 is easy to check. Let $s \in B$, then there is a unique $\widehat{s} \in B^\sharp$ with the properties of the inverse element. Suppose that $\widehat{s} = 0$ then $\widehat{\widehat{s}} = \widehat{0}$, which gives $s = 0$, a contradiction.

b) For $s \in B$ we have $\widehat{s} \in B^\sharp$ such that $s \cdot \widehat{s} \cdot s = s$ and $\widehat{s} \cdot s \cdot \widehat{s} = \widehat{s}$. Now $s \cdot \widehat{s} \in B$ (since if $s \cdot \widehat{s} = 0 \Rightarrow s = 0 \notin B$) and $(s \cdot \widehat{s}) \cdot (s \cdot \widehat{s}) = (s \cdot \widehat{s} \cdot s) \cdot \widehat{s} = s \cdot \widehat{s}$.

c) Suppose that $t \cdot s \neq 0$ and $t \cdot s \in \text{Idemp}(B)$. Then $s \cdot \widehat{s} = \widehat{t} \cdot t$ and $t \cdot s \cdot t \cdot s = t \cdot s$. We multiply the last relation with \widehat{s} on the right and obtain

$$t \cdot s \cdot t \cdot s \cdot \widehat{s} = t \cdot s \cdot \widehat{s} \Rightarrow t \cdot s \cdot t \cdot \widehat{t} \cdot t = t \cdot \widehat{t} \cdot t \Rightarrow t \cdot s \cdot t = t.$$

Similarly we obtain $s \cdot t \cdot s = t$, thus $t = \widehat{s}$. □

From [1] we recall the definition of a symmetric algebra. A k -algebra A is called *symmetric* if it is finitely generated and projective as k -module and there is $\tau : A \rightarrow k$ a central form (that is k -linear map with $\tau(a \cdot a') = \tau(a' \cdot a)$ for all $a, a' \in A$), which induces an isomorphism of $A - A$ -bimodules

$$\widehat{\tau} : A \rightarrow A^*, \widehat{\tau}(a)(b) = \tau(a \cdot b),$$

where $a, b \in A$ and A^* is the k -dual. τ is called *symmetric form* of A and A is *principally symmetric* if τ is onto.

Theorem 1.6. *If A is an inv-symm k -algebra then A is principally symmetric. In particular it is symmetric.*

Proof. By Definition 1.1 A is a finitely generated k -module and free, thus projective. We define the following k -linear form on the basis B

$$\tau_B : A \rightarrow k, \quad \tau_B(s) = \begin{cases} 1_k, & s \in \text{Idemp}(B) \\ 0, & s \notin \text{Idemp}(B) \end{cases}$$

From Lemma 1.5, b) it follows that τ_B is not the zero map and τ_B is a k -linear form. We prove that it is a central form, that is $\tau_B(s \cdot t) = \tau_B(t \cdot s)$ where $t, s \in B$, by considering the cases:

- If $t \cdot s \neq 0$ and $t \cdot s \in \text{Idemp}(B)$, by Lemma 1.5, c) it follows that $\widehat{s} = t$ and then

$$\tau_B(s \cdot \widehat{s}) = 1_k = \tau_B(\widehat{s} \cdot s).$$

- If $t \cdot s \neq 0$ and $t \cdot s \in B \setminus \text{Idemp}(B)$ then $\tau_B(t \cdot s) = 0$. Now, if $s \cdot t \neq 0$ and $s \cdot t \in \text{Idemp}(B)$ by Lemma 1.5, c) we get that $s = \widehat{t}$, which is a contradiction with

$\tau_B(t \cdot s) = 0$. So we have two possibilities: $s \cdot t = 0$, or $s \cdot t \neq 0$ and $s \cdot t \notin \text{Idemp}(B)$. In both subcases $\tau_B(s \cdot t) = 0$.

- If $t \cdot s = 0$ then $\tau_B(t \cdot s) = 0$, and the same analyze to the second case gives us equality.

τ_B induces the following $A - A$ -bimodule homomorphism $\widehat{\tau}_B : A \rightarrow A^*$ defined by

$$\widehat{\tau}_B(t)(s) = \tau_B(t \cdot s)$$

for any $t, s \in B$.

First we prove that $\widehat{\tau}_B$ is injective. Let $t_1, t_2 \in B$ such that $\tau_B(t_1 \cdot s) = \tau_B(t_2 \cdot s)$ for any $s \in B$. We choose $s = \widehat{t}_1$ and obtain that $\tau_B(t_2 \cdot \widehat{t}_1) = 1_k$. It follows that $t_2 \cdot \widehat{t}_1 \neq 0$ and $t_2 \cdot \widehat{t}_1 \in \text{Idemp}(B)$. By Lemma 1.5, c) we obtain that $t_2 = \widehat{t}_1 = t_1$.

For surjectivity let $\lambda \in A^*$ and define $a = \sum_{t \in B} \lambda(t) \cdot \widehat{t} \in A$. Then for $s \in B$

$$\widehat{\tau}_B(a)(s) = \sum_{t \in B} \lambda(t) \tau_B(\widehat{t} \cdot s).$$

Since $\tau_B(\widehat{t} \cdot s) = 1_k$ if and only if $s = t$ we obtain that

$$\widehat{\tau}_B(a)(s) = \lambda(s) \cdot \tau_B(\widehat{s} \cdot s) = \lambda(s).$$

This concludes the proof. □

2. Skew group algebras

In this section we will investigate the skew group algebra associated to a G -algebra which is an inv-symm algebra, where G is a finite group. The Remark 1.4 is the starting point of the next definition.

Definition 2.1. *A G -algebra A is called G -inv-symm if it is inv-symm, with the basis B (from Definition 1.1) G -stable.*

It is easy to show, using Theorem 1.6, that any G -inv-symm algebra is G -permutation and principally symmetric. If A is a G -algebra we denote the action of an $g \in G$ on $a \in A$ by ${}^g a$.

Theorem 2.2. *Let G be a finite group and A a G -algebra. If A is G -inv-symm then the skew group algebra, denoted $A \star G$, is inv-symm. In particular it is principally symmetric.*

Proof. We remind the definition of a skew group algebra. The skew group algebra $A \star G$ is the free A -module of basis

$$\{a \star g \mid a \in A, g \in G\},$$

where $a \star g$ is a notation and the product is given by

$$(a \star g)(b \star h) = a \cdot {}^g b \star gh.$$

Since B is the k -basis of A it is easy to check that the set

$$B \star G = \{s \star g \mid s \in B, g \in G\}$$

is a k -basis of the skew group algebra. Moreover it is a finite semigroup with zero, with the product defined above, since B is G -stable. Next we verify the conditions from Definition 1.1:

(1). We prove that the inverse of $s \star g \in B \star G$ is the element

$$\widehat{s \star g} = g^{-1} \widehat{s} \star g^{-1} \in B \star G.$$

We have

$$(s \star g)(g^{-1} \widehat{s} \star g^{-1})(s \star g) = (s \cdot \widehat{s} \star 1_G)(s \star g) = s \cdot \widehat{s} \cdot {}^{1_G} s \star g = s \star g.$$

Similarly we prove the other statement. Suppose now that there is $t \star h \in B \star G$ such that $(s \star g)(t \star h)(s \star g) = s \star g$. Then we have that

$$(s \cdot {}^g t \star gh)(s \star g) = s \star g \Rightarrow s \cdot {}^g t \cdot {}^{gh} s \star ghg = s \star g.$$

We have that $h = g^{-1}$ and $t = g^{-1} \widehat{s}$, thus it is unique.

(2). Let $s \star g, t \star h \in B \star G$. We have that $(t \star h)(s \star g) \neq 0$ if and only if $t \cdot {}^h s \neq 0$. We also have that

$$\begin{aligned} (s \star g)(g^{-1} \widehat{s} \star g^{-1}) &= ({}^{h^{-1}} \widehat{t} \star h^{-1})(t \star h) \Leftrightarrow s \cdot \widehat{s} \star g = {}^{h^{-1}} \widehat{t} \cdot {}^{h^{-1}} t \star 1_G \Leftrightarrow \\ s \cdot \widehat{s} &= {}^{h^{-1}} (\widehat{t} \cdot t) \Leftrightarrow {}^h s \cdot {}^h \widehat{s} = \widehat{t} \cdot t. \end{aligned}$$

But since A is G -inv-symm the last condition is equivalent to $t \cdot {}^h s \neq 0$, by Definition 1.1, statement(2). \square

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