

On the stability of the bivariate geometric composed distribution's characterization

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Abstract. Let $(X_j, Y_j), j = 1, 2, \dots$ be nonnegative i.i.d random vectors and (N_1, N_2) be independent of $(X_j, Y_j), j = 1, 2, \dots$ with Bivariate Geometric Distribution. The vector $(Z_1 = \sum_{j=1}^{N_1} X_j; Z_2 = \sum_{j=1}^{N_2} Y_j)$ is called the Bivariate Geometric Composed vector. In [3], a characterization for distribution function of this vector was showed and in this paper we shall consider the stability of this characterization.

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1. Introduction

At first, we recall a well-known characterization of the univariate geometric composed distribution. Let X_1, X_2, \dots be nonnegative i.i.d random variables (r.v's) $P(X_j > x) = \bar{F}(x), EX_j = 1 (j = 1, 2, \dots)$ and let N be independent of $X_j, (j = 1, 2, \dots)$ with the Geometric distribution, i.e.

$$P(N = k) = p(1 - p)^{k-1} \quad (k = 1, 2, \dots)$$

The random variable $Z = \sum_{j=1}^N X_j$ is called the Geometric Composed random variable. We denote $\bar{G}_p(x) = P\{pZ > x\}$. In [1], Renyi has given characteristics of this Geometric Composed Distribution. In [2], some stabilities of this Renyi's characteristic theorem was considered by two Vietnamese authors. In [3] (1985), A. Kovat (Hungarian) expanded this Renyi's characteristic theorem for the case of two dimensions.

We consider the Bivariate Geometric Composed distribution as the following definition (See [3]).

Let A_1, A_2 be arbitrary events and $p = (p_1, p_2, p_{12})$, means the probabilities

$$P(A_1 \overline{A_2}) = p_1; P(\overline{A_1} A_2) = p_2; P(A_1 A_2) = p_{12} \tag{1.1}$$

and $q = 1 - p_1 - p_2 - p_{12} = 1 - P(\overline{A_1} \cup \overline{A_2})$.

Let N_1, N_2 be the serial numbers of necessary trials for occurring at first of the event A_1, A_2 resp. occur at first. Then we will say that the random vector (N_1, N_2) has bivariate geometric distribution and we can obtain the following distribution of (N_1, N_2) :

$$P\{N_1 = k_1; N_2 = k_2\} = \begin{cases} q^{k_2-1} p_2 (1 - p_1 - p_{12})^{k_1 - k_2 - 1} (p_1 + p_{12}) & \text{if } k_1 > k_2 \\ q^{k_1-1} p_{12} & \text{if } k_1 = k_2 \\ q^{k_1-1} p_1 (1 - p_2 - p_{12})^{k_2 - k_1 - 1} (p_1 + p_{12}) & \text{if } k_1 < k_2 \end{cases} \tag{1.2}$$

Let $(X_j, Y_j), j = 1, 2, \dots$ be nonnegative i.i.d. random vectors, $P\{X_j > x; Y_j > y\} = \overline{F}(x, y)$, $\varphi(t_1, t_2) = E\{e^{it_1 X_j + it_2 Y_j}\}; EX_j = 1; EY_j = 1 (j = 1, 2, \dots)$

Let (N_1, N_2) be independent of $(X_j, Y_j) (j=1,2,\dots)$ and (N_1, N_2) has Bivariate geometric distribution. The random vector $(Z_1 = \sum_{j=1}^{N_1} X_j; Z_2 = \sum_{j=1}^{N_2} Y_j)$ is called the Bivariate Geometric Composed random vector.

Put

$$\overline{G}_p(x, y) = P\{(p_1 + p_{12})Z_1 > x; (p_2 + p_{12})Z_2 > y\}. \tag{1.3}$$

The following characteristic theorem was showed in [3].

Theorem 1.1 $\overline{G}_p(x, y) = \overline{F}(x, y)$ if and only if

$$\varphi(t_1, t_2) = [1 - it_1 - it_2 + \sum_{r=1}^{\infty} \sum_{k=1}^{\infty} (-1)^{n+k} a_{n,k} t_1^n t_2^k]^{-1}, \tag{1.4}$$

where

$$\begin{aligned} a_{1,1} &= \frac{p_1 + p_2}{p_1 + p_2 + p_{12} - (p_1 + p_{12})(p_2 + p_{12})}, \\ a_{1,2} &= \frac{p_2 - a_{1,1}(p_2 + p_{12})(1 - p_1 - p_{12})}{p_1 + p_2 + p_{12} - (p_1 + p_{12})(p_2 + p_{12})^2}, \\ a_{2,1} &= \frac{p_1 - a_{1,1}(p_1 + p_{12})(1 - p_2 - p_{12})}{p_1 + p_2 + p_{12} - (p_1 + p_{12})^2(p_2 + p_{12})}, \end{aligned} \tag{1.5}$$

$$\begin{aligned} a_{n,k} &= [p_1 + p_2 + p_{12} - (p_1 + p_{12})^n (p_2 + p_{12})^k]^{-1} \\ &\cdot \{a_{n-1,k-1} [(p_1 + p_{12})^{n-1} (p_2 + p_{12})^{k-1} - p_{12}] \\ &+ a_{n,k-1} [(p_1 + p_{12})^n (p_2 + p_{12})^{k-1} - p_2 - p_{12}] \\ &+ a_{n-1,k} [(p_1 + p_{12})^{n-1} (p_2 + p_{12})^k - p_1 - p_{12}]\} \end{aligned}$$

Now, we shall consider the stability of this characteristic theorem.

2. Stability theorems

Suppose that X and Y are two n -dimensional random vectors with the characteristic functions $\varphi_X(t)$ and $\varphi_Y(t)$ respectively. In [4], the metric $\lambda(X; Y)$ was defined as follows

$$\lambda(X; Y) = \lambda(\varphi_X; \varphi_Y) = \sup_{T>0} \left\{ \max\{v(X, Y; T); \frac{1}{T}\} \right\} \quad (2.1)$$

where

$$v(X, Y; T) = \frac{1}{2} \max\{|\varphi_X(t) - \varphi_Y(t)|; \|t\| < T\} \quad (2.2)$$

and $\varphi_X(t) = Ee^{i(t, X)}$, where (\cdot, \cdot) denotes the scalar product in the space \mathbb{R}^n and $\|t\| = \sqrt{(t, t)}$ with $t \in \mathbb{R}^n$.

Theorem 2.1. *Let us consider the 2-dimensional characteristic function*

$$\varphi_0(t_1, t_2) = [1 - it_1 - it_2 + \sum_{n=1}^{\infty} \sum_{k=1}^{\infty} (-1)^{n+k} a_{n,k} t_1^n t_2^k]^{-1}, \quad (2.3)$$

where $a_{n,k}$ was given in (1.5).

If X_j and Y_j (with $j = 1, \dots, n$) has the same ϵ -exponential distribution, i.e. $\exists T_1(\epsilon) > 0, T_2(\epsilon) > 0$ (such that $T_1(\epsilon) \rightarrow \infty$ and $T_2(\epsilon) \rightarrow \infty$ when $\epsilon \rightarrow 0$) and such that

$$\left| \varphi_{X_j}(t_1) - \frac{1}{1 - it_1} \right| \leq \epsilon \quad \forall t_1, \quad |t_1| \leq T_1(\epsilon), \quad \forall j, \quad (2.4)$$

$$\left| \varphi_{Y_j}(t_2) - \frac{1}{1 - it_2} \right| \leq \epsilon \quad \forall t_2, \quad |t_2| \leq T_2(\epsilon), \quad \forall j, \quad (2.5)$$

then, for every characteristic function $\varphi(t_1, t_2)$ of the random vector (X_j, Y_j) , we always have the estimation

$$\lambda(\varphi; \varphi_0) = \lambda[\varphi(t_1, t_2); \varphi_0(t_1, t_2)] \leq \max(C_1\epsilon; \frac{1}{T^*(\epsilon)}), \quad (2.6)$$

where $T^*(\epsilon) = \min[T_1(\epsilon); T_2(\epsilon)]$ and C is a constant independent of ϵ .

Proof of the Theorem 2.1. From the proof of Theorem 2 in [3] or see [5], we have

$$\varphi(t_1, t_2) = \varphi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2][p_{12} + p_1\varphi(0, t_2) + p_2\varphi(t_1, 0) + q\varphi(t_1, t_2)]$$

and

$$\varphi(t_1, t_2) = \frac{\varphi[(p_{12} + p_1)t_1, (p_{12} + p_2)t_2][p_{12} + p_1\varphi(0, t_2) + p_2\varphi(t_1, 0)]}{1 - q\varphi[(p_{12} + p_1)t_1, (p_{12} + p_2)t_2]}. \quad (2.7)$$

Thus, we shall have the estimation

$$\begin{aligned} & |\varphi(t_1, t_2) - \varphi_0(t_1, t_2)| \\ &= \left| \frac{\varphi[(p_{12} + p_1)t_1, (p_{12} + p_2)t_2][p_{12} + p_1\varphi(0, t_2) + p_2\varphi(t_1, 0)]}{1 - q\varphi[(p_{12} + p_1)t_1, (p_{12} + p_2)t_2]} - \varphi_0(t_1, t_2) \right|. \end{aligned} \quad (2.8)$$

But from (2.4) and (2.5), $\exists T^*(\epsilon) = \min\{T_1(\epsilon); T_2(\epsilon)\}$ such that

$$\varphi(0, t_2) = \frac{1}{1 - it_2} + r_2(t_2) \quad \text{where } |r_2(t_2)| \leq \epsilon, \quad \forall t_2, \quad |t_2| \leq T^*(\epsilon) \quad (2.9)$$

$$\varphi(t_1, 0) = \frac{1}{1 - it_1} + r_1(t_1) \text{ where } |r_1(t_1)| \leq \epsilon, \quad \forall t_1, \quad |t_1| \leq T^*(\epsilon). \quad (2.10)$$

On the other hand, from formula (2.8) of the proof of the Theorem 2 in [3], we obtain also the following equality

$$\varphi_0(t_1, t_2) = \frac{\varphi_0[(p_{12} + p_1)t_1, (p_{12} + p_2)t_2][p_{12} + \frac{p_1}{1 - it_1} + \frac{p_2}{1 - it_2}]}{1 - q\varphi_0[(p_{12} + p_1)t_1, (p_{12} + p_2)t_2]}. \quad (2.11)$$

Taking into account (2.8), (2.9), (2.10) and (2.11) we get

$$|\varphi(t_1, t_2) - \varphi_0(t_1, t_2)| = \left| \frac{\varphi_0[(p_{12} + p_1)t_1, (p_{12} + p_2)t_2]}{1 - q\varphi_0[(p_{12} + p_1)t_1, (p_{12} + p_2)t_2]} \right| |r^*(t_1, t_2)|, \quad (2.12)$$

where $r^*(t_1, t_2) = p_1 r_1(t_1) + p_2 r_2(t_2)$ and from (2.9) and (2.10) we notice that

$$|r^*(t_1, t_2)| = |p_1 r_1(t_1) + p_2 r_2(t_2)| \leq C\epsilon,$$

for all $|t_1| \leq T_1(\epsilon), |t_2| \leq T_2(\epsilon)$.

On the other hand, we always have the inequalities:

$$|1 - qz| \geq |1 - q|z| \geq 1 - q \quad (2.13)$$

for all complex number $z, |z| \leq 1$.

So, we have

$$|\varphi(t_1, t_2) - \varphi_0(t_1, t_2)| \leq \frac{r^*(t_1, t_2)}{1 - q} \leq \frac{C\epsilon}{1 - q} = C_1\epsilon, \quad (2.14)$$

where C_1 is a constant of ϵ . The proof Theorem 2.1 is completed.

Let us denote the characteristic function corresponding to $\overline{G_p}(x, y)$ by $\psi_p(t_1, t_2)$. Now, we consider the second stability theorem.

Theorem 2.2. *If both X_j and Y_j have ϵ -exponential distribution ($j = 1, 2, \dots, n$) as described in Theorem 2.1, then we have the inequality*

$$\lambda(\psi_p, \varphi_0) = \lambda[\psi_p(t_1, t_2); \varphi_0(t_1, t_2)] \leq \max\{C_2\epsilon; \frac{1}{T^*(\epsilon)}\} \quad (2.15)$$

Proof of Theorem 2.2. At first, denoting by $\psi(t_1, t_2)$ the characteristic function of (Z_1, Z_2) , then

$$\psi_p(t_1, t_2) = \psi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2].$$

But, in the proof of Theorem 1 in [3], we have

$$\begin{aligned} & \psi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2] \\ &= \frac{\varphi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2][p_{12} + p_1\psi(0, t_2) + p_2\psi(t_1, 0)]}{1 - \varphi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2]}; \end{aligned} \quad (2.16)$$

in [2], we have already proved that if X_j is ϵ -exponentially distributed then

$$|\psi(t_1, 0) - \frac{1}{1 - it_1}| = |r_1(t_1)| \leq \max_{|t_1| \leq T_1(\epsilon)} \left\{ \frac{\epsilon}{2}; \frac{1}{T_1(\epsilon)} \right\} \quad \forall t_1, \quad |t_1| \leq T_1(\epsilon) \quad (2.17)$$

and, more, if Y_j is ϵ -exponentially distributed then

$$|\psi(0, t_2) - \frac{1}{1 - it_2}| = |r_2(t_2)| \leq \max_{|t_2| \leq T_1(\epsilon)} \left\{ \frac{\epsilon}{2}; \frac{1}{T_2(\epsilon)} \right\} \quad \forall t_2, \quad |t_2| \leq T_2(\epsilon), \tag{2.18}$$

and from (2.16), (2.17) and (2.18) it follows that

$$\begin{aligned} & \psi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2] \\ &= \frac{\varphi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2] \left[p_{12} + \frac{p_1}{1 - it_1} + \frac{p_2}{1 - it_2} \right]}{1 - q\varphi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2]} \\ & \quad + \frac{\varphi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2] [p_1 r_1(t_1) + p_2 r_2(t_2)]}{1 - q\varphi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2]} \end{aligned} \tag{2.19}$$

Therefore

$$\begin{aligned} & |\psi_p(t_1, t_2) - \varphi_0(t_1, t_2)| \\ & \leq \left| \frac{\varphi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2] \left[p_{12} + \frac{p_1}{1 - it_1} + \frac{p_2}{1 - it_2} \right]}{1 - q\varphi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2]} - \varphi_0(t_1, t_2) \right| \\ & \quad + \left| \frac{\varphi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2]}{1 - q\varphi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2]} \right| |p_1 r_1(t_1) + p_2 r_2(t_2)| = J_1 + J_2. \end{aligned} \tag{2.20}$$

Taking into account (2.9), (2.10) and (2.13), we get

$$J_2 \leq \max \left\{ C_2 \epsilon; \frac{1}{T^*(\epsilon)} \right\} \tag{2.21}$$

where $T^*(\epsilon) = \min\{T_1(\epsilon); T_2(\epsilon)\}$ and C_2 is a constant of ϵ .

According to the proof of Theorem 2 in [3], we have

$$\varphi_0(t_1, t_2) = \frac{\varphi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2] \left[p_{12} + \frac{p_1}{1 - it_1} + \frac{p_2}{1 - it_2} \right]}{1 - q\varphi[(p_{12} + p_1)t_1; (p_{12} + p_2)t_2]}. \tag{2.22}$$

Thus, $J_1 = 0$ and we have:

$$J_1 + J_2 \leq \max \left\{ C_2 \epsilon; \frac{1}{T^*(\epsilon)} \right\}. \tag{2.23}$$

where C_2 is a constant independent of ϵ . Therefore it follows that

$$\lambda(\psi_P; \varphi_0) \leq \max \left\{ C_2 \epsilon; \frac{1}{T^*(\epsilon)} \right\} \tag{2.24}$$

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