

A MONOTONY METHOD IN QUASISTATIC PROCESSES FOR VISCOPLASTIC MATERIALS

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Abstract. In this paper, we study a quasistatic problem for semi-linear rate-type viscoplastic models with two parameters χ, θ ; χ may be interpreted as the absolute temperature or an internal state variable. The existence and uniqueness of the solution is proved using monotony arguments followed by a Cauchy-Lipschitz technique.

1. Introduction

Throughout the paper, Ω is a bounded in $IR^N (N = 1, 2, 3)$ with a smooth boundary $\partial\Omega = \Gamma$ and Γ_1 is an open subset of Γ such that $meas\Gamma_1 > 0$. We denote $\Gamma_2 = \Gamma - \bar{\Gamma}_1$. Let ν be the outward unit normal vector on Γ and S_N the set of second order symmetric tensors on IR^N . Let T be a real positive constant. LET us the mixed problem.

$$\dot{\sigma} = \mathcal{E}(\varepsilon(\dot{u}), \theta, \chi) + F(\sigma, \varepsilon(u), \theta) \quad \text{in } \Omega \times (0, T) \quad (1)$$

$$Div \sigma + f = 0 \quad \text{in } \Omega \times (0, T) \quad (2)$$

$$u = g \quad \text{on } \Gamma_1 \times (0, T) \quad (3)$$

$$\sigma\nu = h \quad \text{on } \Gamma_2 \times (0, T) \quad (4)$$

$$u(0) = u_0, \quad \sigma(0) = \sigma_0 \quad \text{in } \Omega \quad (5)$$

in which the unknowns are the displacement function $u : \Omega \times [0, T] \rightarrow R^N$, the stress function $\sigma : \Omega \times [0, T] \rightarrow S_N$ This problem represents a quasistatic problem for rate-type models of the form (1) in with ε is a nonlinear function depending on

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$\varepsilon(\dot{u})$, θ and χ , are parameters and $\varepsilon(u) : \Omega \times [0, T] \rightarrow S_N$ is the small strain tensor (i.e. $\varepsilon(u) = \frac{1}{2}\nabla u + \nabla^t u$). In (1) \mathcal{E} and F are given constitutive function .

In (2) $Div \sigma$ represent the divergence of vector valued function σ and f represents the given body force, g and h are the given bounded data and, finally, u_0, σ_0 are the initial data.

In the case when ε depends only on χ , existence and uniqueness results for problems of the form (1)-(5) was obtained by Sofonea (1991) reducing the studied problem to an ordinary differential equation in a Hilbert space. In the case when \mathcal{E} is a nonlinear function depending only on $\varepsilon(\dot{u})$ and χ existence and uniqueness results for problems of the form (1)-(5) was obtained by Djabi (1993) using monotony arguments followed by a Cauchy-Lipschitz technique.

The purpose of this paper is to give a now proof for the existence and uniqueness of the solution for the problem (1)-(5) there based only on monotony arguments followed by a Cauchy-Lipschitz technique (theorem 3.1).

2. Notations and preliminaries

Everywhere in this paper we utilize the following notations: " " the inner product on the spaces \mathbb{R}^N , \mathbb{R}^M and S_N and $|\cdot|$ are the Euclidean norms on these spaces.

$$H = \{ v = (v_i) \mid v_i \in L^2(\Omega), i = \overline{1, N} \},$$

$$H_1 = \{ v = (v_i) \mid v_i \in H^1(\Omega), i = \overline{1, N} \},$$

$$\mathcal{H} = \{ \tau = (\tau_{ij}) \mid \tau_{ij} = \tau_{ji} \in L^2(\Omega), i, j = \overline{1, N} \},$$

$$\mathcal{H}_1 = \{ \tau = (\tau_{ij}) \mid Div \tau \in H \},$$

$$Y = \{ \kappa = (\kappa_i) \mid \kappa_i \in L^2(\Omega), i = \overline{1, M} \}.$$

The spaces H , H_1 , \mathcal{H} , \mathcal{H}_1 and Y are real Hilbert spaces endowed with the canonical inner products denoted by $\langle \cdot, \cdot \rangle_H$, $\langle \cdot, \cdot \rangle_{H_1}$, $\langle \cdot, \cdot \rangle_{\mathcal{H}}$, $\langle \cdot, \cdot \rangle_{\mathcal{H}_1}$ and $\langle \cdot, \cdot \rangle_Y$ respectively.

Let $H_\Gamma = [H^{\frac{1}{2}}(\Gamma)]^N$ and $\gamma : H_1 \rightarrow H_\Gamma$ be the trace map. We denote by

$$V = \{ u \in H_1 \mid \gamma u = 0 \text{ on } \Gamma_1 \}$$

and let E be the subspace of H_Γ defined by

$$E = \gamma(V) = \{ \xi \in H_\Gamma \mid \xi = 0 \text{ on } \Gamma_1 \}. \quad (6)$$

Let $H'_\Gamma = [H^{-\frac{1}{2}}(\Gamma)]^N$ be the strong dual of the space H_Γ and let $\langle \cdot, \cdot \rangle$ denote the duality between H'_Γ and H_Γ . If $\tau \in \mathcal{H}_1$ there exists an element $\gamma_\nu \tau \in H'_\Gamma$ such that

$$\langle \gamma_\nu \tau, \gamma v \rangle = \langle \tau, \varepsilon(v) \rangle_{\mathcal{H}} + \langle \text{Div } \tau, v \rangle_H \text{ for all } v \in H_1. \quad (7)$$

By τ_ν we shall understand the element of E' (the strong dual of E) that is the projection of $\gamma_\nu \tau$ on E .

Let us now denote by \mathcal{V} the following subspace of \mathcal{H}_1 .

$$\mathcal{V} = \{ \tau \in \mathcal{H}_1 \mid \text{Div } \tau = 0 \text{ in } \Omega, \tau_\nu = 0 \text{ on } \Gamma_2 \}$$

Using (7), it may be proved that $\varepsilon(V)$ is the orthogonal complement of \mathcal{V} in \mathcal{H} , hence

$$\langle \tau, \varepsilon(v) \rangle_{\mathcal{H}} = 0, \text{ for all } v \in V, \tau \in \mathcal{V}. \quad (8)$$

Finally, for every real Hilbert space X we denote by $|\cdot|_X$ the norm on X and by $C^j(0, T, X)$ ($j = 0, 1$) the spaces defined as follows:

$$C^0(0, T, X) = \{ z : [0, T] \rightarrow X \mid z \text{ is continuous} \}.$$

Let us recall that if $C^j(0, T, X)$ are real Banach spaces endowed with the norms

$$C^1(0, T, X) = \{ z : [0, T] \rightarrow X \mid \text{there exists } \dot{z} \text{ the derivate of } z \text{ and } \dot{z} \in C^0(0, T, X) \}.$$

$$|z|_{0,T,X} = \max_{t \in [0,T]} |z(t)|_X \quad (9)$$

and

$$|z|_{1,T,X} = |z|_{0,T,X} + |\dot{z}|_{0,T,X}$$

respectively.

Let us recall that if K is a convex closed non empty set of X and $P : X \rightarrow K$ is the projector map on K , we have

$$y = Px \text{ if only if } y \in K \text{ and } \langle y - x, z - x \rangle_X \geq 0 \text{ for all } z \in K. \quad (10)$$

3. An existence and uniqueness result

In the study of the problem (1)-(5), we consider the following assumptions:

$$\left\{ \begin{array}{l} \mathcal{E} : \Omega \times S_N \times L^2(\Omega)^p \times L^2(\Omega)^M \rightarrow S_N \text{ and} \\ \text{(a) there exists } m > 0 \text{ such that} \\ \langle \mathcal{E}(\varepsilon_1, \theta, \chi) - \mathcal{E}(\varepsilon_2, \theta, \chi), \varepsilon_1 - \varepsilon_2 \rangle \geq \\ \geq m|\varepsilon_1 - \varepsilon_2|^2 \text{ for all } \varepsilon_1, \varepsilon_2 \in S_N, \theta \in L^2(\Omega)^p, \chi \in L^2(\Omega)^M \text{ a.e. in } \Omega, \\ \text{(b) there exists } L' > 0 \text{ such that} \\ |\mathcal{E}(\varepsilon_1, \theta_1, \chi_1) - \mathcal{E}(\varepsilon_2, \theta_2, \chi_2)| \leq L'|\varepsilon_1 - \varepsilon_2| + |\theta_1 - \theta_2| + |\chi_1 - \chi_2| \\ \text{for all } \varepsilon_1, \varepsilon_2 \in S_N, \text{ a.e. in } \Omega, \\ \text{(c) } x \rightarrow \mathcal{E}(x, \varepsilon, \theta, \chi) \text{ is a measurable function with respect to} \\ \text{the lebesgue measure in } \Omega \text{ for all } \varepsilon \in S_N, \\ \text{(d) } x \rightarrow \mathcal{E}(x, 0, 0, 0) \in \mathcal{H} \end{array} \right. \quad (11)$$

$$\left\{ \begin{array}{l} F : \Omega \times S_N \times S_N \times L^2(\Omega)^p \times L^2(\Omega)^M \rightarrow S_N \text{ and} \\ \text{a) there exists } L > 0 \text{ such that} \\ |F(x, \sigma_1, \varepsilon_1, \theta_1, \chi_1) - F(x, \sigma_2, \varepsilon_2, \theta_2, \chi_2)| \leq \\ \leq L(|\sigma_1 - \sigma_2| + |\varepsilon_1 - \varepsilon_2| + |\theta_1 - \theta_2| + |\chi_1 - \chi_2|) \\ \text{(b) } x \rightarrow F(x, \sigma, \varepsilon, \theta, \chi) \text{ is a measurable function with respect to} \\ \text{the Lebesgue measure on } \Omega, \text{ for all } \sigma, \varepsilon \in S_N, \kappa \in \mathbb{R}^M, \theta \in \mathbb{R}^P, \\ \text{(c) } x \rightarrow F(x, 0, 0, 0, 0) \in \mathcal{H}. \end{array} \right. \quad (12)$$

$$f \in C^1(0, T, H), \quad g \in (0, T, H_\Gamma), \quad h \in C^1(0, T, E') \quad (13)$$

$$u_0 \in H_1, \quad \sigma_0 \in \mathcal{H}_1 \quad (14)$$

$$\text{Div } \sigma_0 + f(0) = 0 \text{ in } \Omega, \quad u_0 = g(0) \text{ on } \Gamma_1, \quad \sigma_0 \nu = h(0) \text{ on } \Gamma_2. \quad (15)$$

$$\theta \in C^0(0, T, L^2(\Omega)^P), \chi \in C^0(0, T, L^2(\Omega)^M) \quad (16)$$

The main result of this section is as follows.

Theorem 3.1. Let (11)-(16) hold. Then there exists a unique solution $u \in C^1(0, T, H_1)$, $\sigma \in C^1(0, T, \mathcal{H}_1)$ of the problem (1)-(5). In order to prove theorem 3.1, we need some preliminaries.

Let $\tilde{u} \in C^1(0, T, H_1)$, $\tilde{\sigma} \in C^1(0, T, \mathcal{H}_1)$ be two functions such that

$$\text{Div } \tilde{\sigma} + f = 0 \text{ in } \Omega \times (0, T) \quad (17)$$

$$\tilde{u} = g \text{ on } \Gamma_1 \times (0, T) \quad (18)$$

$$\tilde{\sigma}\nu = h \text{ on } \Gamma_2 \times (0, T) \quad (19)$$

(the existence of this couple follows from (13) and the properties of the trace maps).

Considering the functions defined by

$$\bar{u} = u - \tilde{u}, \quad \bar{\sigma} = \sigma - \tilde{\sigma}, \quad (20)$$

$$\bar{u}_0 = u_0 - \tilde{u}_0, \quad \bar{\sigma}_0 = \sigma_0 - \tilde{\sigma}_0, \quad (21)$$

it easy to see that the triplet $(u, \sigma) \in C^1(0, T, H \times \mathcal{H}_1)$ is a solution of the problem (1)-(5) if and only if

$$(\bar{u}, \bar{\sigma}) \in C^1(0, T, V \times \mathcal{V}) \quad (22)$$

$$\dot{\sigma} = \mathcal{E}(\varepsilon(\dot{u}) + \varepsilon(\dot{\tilde{u}}), \theta, \chi) + F(\bar{\sigma} + \tilde{\sigma}, \varepsilon(\bar{u}) + \varepsilon(\tilde{u}), \theta, \chi) - \dot{\tilde{\sigma}} \text{ in } \Omega \times (0, T) \quad (23)$$

$$\bar{u}(0) = \bar{u}_0, \quad \bar{\sigma}(0) = \bar{\sigma}_0 \text{ in } \Omega \quad (24)$$

hence we may write (22)-(24) in the form

$$\dot{y}(t) = \mathcal{G}(\theta(t), \chi(t), x(t), y(t), \dot{x}(t)) \quad (25)$$

$$x(0) = x_0, \quad y(0) = y_0 \quad (26)$$

In which the unknowns are the function $x : [0, T] \rightarrow X$ and $y : [0, T] \rightarrow Y$ $\mathcal{G} : L^2(\Omega)^p \times L^2(\Omega)^M \times X \times Y \times H \rightarrow H$ is a nonlinear operator, and $X : [0, T] \rightarrow L^2(\Omega)^M$, $\theta : [0, T] \rightarrow L^2(\Omega)^p$ are parameters, where H is a real Hilbert space, X, Y , are two orthogonal subspaces of H such that $H = X \oplus Y$ and $L^2(\Omega)^M, L^2(\Omega)^p$, are real normed space.

Hence (22)-(24) may be written in the form (25)-(26) where

$$y = \bar{\sigma}, \quad x = \varepsilon(\bar{u}), \quad \dot{x} = \varepsilon(\dot{\bar{u}})$$

and replacing the spaces $\varepsilon(V), \mathcal{V}, \mathcal{H}$, by X, Y, \mathbf{H} respectively.

For resolving the problem (22)-(24), we consider the product Hilbert space $Z = \varepsilon(V) \times V$ which $H = \varepsilon(V) \oplus V$, and the problem \mathcal{G} defined by

$$\mathcal{G} : L^2(\Omega)^p \times L^2(\Omega)^M \times \varepsilon(V) \times v \times H \rightarrow H$$

$$\mathcal{G}(\theta, \chi, x, y, q) = \mathcal{E} \left(q + \varepsilon(\dot{\tilde{u}}), \dot{\theta}(t), \chi(t) \right) + F(y + \bar{\sigma}(t), x + \varepsilon(\tilde{u}), \theta(t), \chi(t)) - \dot{\bar{\sigma}}(t) \quad (27)$$

We have the following result.

Lemma 3.1. Let $\theta(t) \in L^2(\Omega)^P, \chi(t) \in L^2(\Omega)^M, x \in X, y \in Y$ and $t \in [0, T]$.

Then there exists a unique element $z = (\varepsilon(v), \tau) \in Z$ such that

$$\tau = \mathcal{G}(\theta, \chi, x, y, \varepsilon(v)) \quad (28)$$

Proof. The uniqueness part is a consequence of (11); indeed, if

$$z_1 = (\varepsilon(v_1), \tau_1), \quad z_2 = (\varepsilon(v_2), \tau_2) \in Z$$

are such that

$$\tau_1 = \mathcal{G}(\theta, \chi, x, y, \varepsilon(v_1))$$

$$\tau_2 = \mathcal{G}(\theta, \chi, x, y, \varepsilon(v_2)),$$

using (11-a) we have

$$\begin{aligned} \langle \tau_1 - \tau_2, \varepsilon(v_1) - \varepsilon(v_2) \rangle_{\mathcal{H}} &= \\ \left\langle \mathcal{E}(\varepsilon(v_1) + \varepsilon(\dot{\tilde{u}}(t)), \theta(t), \chi(t)) - \mathcal{E}(\varepsilon(v_2) + \varepsilon(\dot{\tilde{u}}(t)), \theta(t), \chi(t)), \varepsilon(v_1) - \varepsilon(v_2) \right\rangle_{\mathcal{H}} & \\ \geq m |\varepsilon(v_1) - \varepsilon(v_2)|_{\mathcal{H}} & \end{aligned}$$

Using now the orthogonality in H of $(\tau_1 - \tau_2) \in \mathcal{V}$ and $(\varepsilon(v_1) - \varepsilon(v_2)) \in \varepsilon(V)$, we deduce that $\varepsilon(v_1) = \varepsilon(v_2)$, which implies $\tau_1 = \tau_2$.

For the existence part, let us consider the operator $S : \varepsilon(V) \rightarrow \varepsilon(V)$ given by $S = P \circ \mathcal{G}$, where P is the projector map $\varepsilon(V)$.

Using now the hypothesis \mathcal{E} , F and the properties of the projectors, we can prove for θ, χ, x, y fixed, the following inequalities:

$$\left\{ \begin{array}{l} \langle S(\theta, \chi, x, y, q_1) - S(\theta, \chi, x, y, q_2), q_1 - q_2 \rangle_{\mathcal{H}} \geq \\ \geq \langle \mathcal{G}(\theta, \chi, x, y, q_1) - \mathcal{G}(\theta, \chi, x, y, q_2), q_1 - q_2 \rangle_{\mathcal{H}} \geq \\ \geq m |q_1 - q_2|_{\mathcal{H}}^2. \end{array} \right. \quad (29)$$

Moreover, from (11), (12), and the properties of the projectors, we get

$$\left\{ \begin{array}{l} |S(\theta, \chi, x, y, q_1) - S(\theta, \chi, x, y, q_2)|_{\mathcal{H}} \leq \\ \leq |\mathcal{G}(\theta, \chi, x, y, q_1) - \mathcal{G}(\theta, \chi, x, y, q_2)|_{\mathcal{H}} \leq \\ \leq L' |q_1 - q_2|_{\mathcal{H}}^2. \end{array} \right. \quad (30)$$

Hence $S(\theta, x, y, \cdot) : \varepsilon(V) \rightarrow \varepsilon(V)$ is a strongly monotone Lipschitz operator. Using now Browder's surjectivity theorem we get that there exists $\varepsilon(v) \in \varepsilon(V)$ such that $S(\theta, \chi, x, y, \varepsilon(v)) = 0_{\varepsilon(V)}$. It results that the element $\mathcal{G}(\theta, \chi, x, y, \varepsilon(v))$ belongs to \mathcal{V} and we finish the proof using $z = (\varepsilon(v), \tau)$ where

$$\tau = \mathcal{G}(\theta, \chi, x, y, \varepsilon(v)).$$

The previous lemma allows to consider the operator $B : L^2(\Omega)^P \times L^2(\Omega)^M \times Z \rightarrow Z$ defined as follows:

$$\left\{ \begin{array}{l} B(\theta, \chi, \omega) = z \\ \omega = (x, y), z = (\varepsilon(v), \tau) \\ \tau = \mathcal{G}(\theta, \chi, x, y, \varepsilon(v)). \end{array} \right. \quad (31)$$

Moreover we have

Lemma 3.2. For all $\theta \in L^2(\Omega)^P$ and $\chi \in L^2(\Omega)^M$ $\omega_1, \omega_2 \in Z$, the operator $L^2(\Omega)^P \times L^2(\Omega)^M \times Z \rightarrow Z$ is continuous and there exists $C > 0$ such that

$$|B(\theta, \chi, \omega_1) - B(\theta, \chi, \omega_2)|_Z \leq C |\omega_1 - \omega_2|_Z \quad (32)$$

for all $\theta \in L^2(\Omega)^P$ and $\chi \in L^2(\Omega)^M$ $\omega_1, \omega_2 \in Z$.

Proof. Let $\theta_i \in L^2(\Omega)^P$, $\omega_i = (x_i, y_i) \in Z$ and

$$z_i = (\varepsilon(v_i), \tau_i) = B(\theta_i, \chi_i, \omega_i), \quad i = 1, 2.$$

Using (32)

$$\tau_i = \mathcal{G}(\theta_i, \chi_i, x_i, y_i, \varepsilon(v_i)), \quad i = 1, 2 \quad (33)$$

which implies

$$S(\theta_i, \chi_i, x_i, y_i, \varepsilon(v_i)) = 0_{\varepsilon(V)}, \quad i = 1, 2. \quad (34)$$

Using the hypothesis on \mathcal{E} , F , and the properties of the projectors, we get:

$$\begin{aligned} m|\varepsilon(v_1) - \varepsilon(v_2)|_{\mathcal{H}}^2 &\leq S(\theta_1, \chi_1, x_1, y_1, \varepsilon(v_1)) \\ &\quad - S(\theta_1, \chi_1, x_1, y_1, \varepsilon(v_2)), \varepsilon(v_1) - \varepsilon(v_2) \rangle_{\mathcal{H}} \\ &= \langle S(\theta_2, \chi_2, x_2, y_2, \varepsilon(v_2)) - S(\theta_1, \chi_1, x_1, y_1, \varepsilon(v_2)), \varepsilon(v_1) - \varepsilon(v_2) \rangle_{\mathcal{H}} \leq \\ &\leq |\mathcal{G}(\theta_2, \chi_2, x_2, y_2, \varepsilon(v_2)) - \mathcal{G}(\theta_1, \chi_1, x_1, y_1, \varepsilon(v_2))|_{\mathcal{H}} \times |\varepsilon(v_1) - \varepsilon(v_2)|_{\mathcal{H}}^2 \end{aligned}$$

which implies

$$|\varepsilon(v_1) - \varepsilon(v_2)|_{\mathcal{H}} \leq \frac{1}{m} \times |\mathcal{G}(\theta_2, \chi_2, x_2, y_2, \varepsilon(v_2)) - \mathcal{G}(\theta_1, \chi_1, x_1, y_1, \varepsilon(v_2))|_{\mathcal{H}}. \quad (35)$$

Using now (12), (34) we get

$$\begin{cases} |\tau_1 - \tau_2|_{\mathcal{H}} \leq L'|\varepsilon(v_1) - \varepsilon(v_2)|_{\mathcal{H}} + \\ |\mathcal{G}(\theta_1, \chi_1, x_1, y_1, \varepsilon(v_2)) - \mathcal{G}(\theta_2, \chi_2, x_2, y_2, \varepsilon(v_2))|_{\mathcal{H}} \end{cases} \quad (36)$$

Hence by (36) it result

$$\begin{cases} |\tau_1 - \tau_2|_{\mathcal{H}} \leq \\ \leq (\frac{L'}{m} + 1)|\mathcal{G}(\theta_1, \chi_1, x_1, y_1, \varepsilon(v_2)) - \mathcal{G}(\theta_2, \chi_2, x_2, y_2, \varepsilon(v_2))|_{\mathcal{H}} \end{cases} \quad (37)$$

Using now (11)-(12)(27) and the fact that $\bar{\sigma}, \dot{\bar{\sigma}}$ are continuous, we get that

$$|\mathcal{G}(\theta_1, \chi_1, x_1, y_1, \varepsilon(v_2)) - \mathcal{G}(\theta_2, \chi_2, x_2, y_2, \varepsilon(v_2))|_{\mathcal{H}} \rightarrow 0$$

When $\theta_1 \rightarrow \theta_2$, in $L^2(\Omega)^P$ $x_1 \rightarrow x_2$ in X , $y_1 \rightarrow y_2$ in Y it follows that B is continuous operator. Taking $\theta_1 = \theta_2$ and $X_1 = X_2$ from (37) we get (33).

Proof of theorem 3.1. Let $A : [0.T] \times Z \rightarrow Z$ and z_0 be defined by:

$$\{A(t, z) = B(\theta(t), \chi(t), z) \text{ for all } t \in [0.T] \text{ and } z \in Z \quad (38)$$

$$z_0 = (x_0, y_0) = \varepsilon((u_0), \bar{\sigma}_0).$$

Using the definition of operator B , we get that

$$x = \varepsilon(\dot{u}) \in C^1(0, T, \varepsilon(V)) \in C^1(0, T, Z'), y = \bar{\sigma} \in C^1(0, T, \mathcal{V})$$

is solution to (22)-(24), if and only

$$\dot{z} = (\dot{x}, \dot{y}) = A(\theta, z(t)) \text{ for all } t \in [0, T] \quad (39)$$

$$z(0) = z_0 \quad (40)$$

In order to study the problem (39)-(40), let us remark that, by lemma 3.2, A is a continuous operator and

$$|A(t, z_1) - A(t, z_2)|_Z \leq C|z_1 - z_2|_Z, \text{ for all } t \in [0, T] \text{ and } z_1, z_2 \in Z.$$

Moreover, by (14), (38), $\tilde{u} \in C^1(0, T, H_1)$ and $\bar{\sigma} \in C^1(0, T, \mathcal{H}_1)$

We get z_0 belongs to Z and by lemma 3.2 and the classical Cauchy-Lipschitz theorem we have that $z \in C^1(0, T, Z)$ and the proof of theorem 3.1 is complete.

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