

**ON THE INVARIANCE PROPERTY  
OF THE FISHER INFORMATION (II)**

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**Abstract.** The objective of this paper is to give some properties for the Fisher's information measure when  $X_{a \leftrightarrow b}$  represents a bilateral truncated random variable that corresponds to a normal random variable  $X$  with the probability density function  $f(x; \theta)$ , where  $\theta = (m, \sigma^2)$ ,  $\theta \in D_\theta$ ,  $D_\theta \subseteq \mathbb{R}^2$ ,  $m \in \mathbb{R}$ ,  $m$ -known parameter,  $\sigma^2 \in \mathbb{R}^+$ ,  $\sigma^2$ -unknown parameter.

**1. Bilateral truncation effect of a normal distribution on Fisher's information**

The Fisher's invariance property will be studied in the case of a truncated normal distribution.

Let  $X$  be a normal distribution with probability density function

$$f(x; m, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp \left\{ -\frac{1}{2} \left( \frac{x-m}{\sigma} \right)^2 \right\}, x \in \mathbb{R}, \quad (1)$$

where the parameters  $m$  and  $\sigma$  have their usual significance, namely:  $m = E(X)$ ,  $\sigma^2 = Var(X)$ ,  $m \in \mathbb{R}$ ,  $\sigma > 0$ .

**Definition 1.** [2] We say that the random variable  $X$  has a normal distribution truncated to the left at  $X = a$ ,  $a \in \mathbb{R}$  and to the right at  $X = b$ ,  $b \in \mathbb{R}$ , denoted by  $X_{a \leftrightarrow b}$ , if its probability density function, denoted by  $f_{a \leftrightarrow b}(x; m, \sigma^2)$ , has the form

$$f_{a \leftrightarrow b}(x; m, \sigma^2) = \begin{cases} \frac{k(a, b)}{\sqrt{2\pi}\sigma} \exp \left\{ -\frac{1}{2} \left( \frac{x-m}{\sigma} \right)^2 \right\} & \text{if } a \leq x \leq b, \\ 0 & \text{if } x < a \text{ or } x > b, \end{cases} \quad (2)$$

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where

$$k(a, b) = \frac{1}{A} = \frac{1}{\Phi\left(\frac{b-m}{\sigma}\right) - \Phi\left(\frac{a-m}{\sigma}\right)}, \quad (3)$$

and

$$\Phi(z) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^z \exp\left(-\frac{t^2}{2}\right) dt, \quad (4)$$

is the standard normal distribution function.

**Theorem 1.** *If the random variable  $X_{a \leftrightarrow b}$  has a bilateral truncated normal distribution, that is its probability distribution has the form (2), then the Fisher's information measure about the unknown parameter  $\sigma^2$ , then the parameter  $m$  is known, has the following form*

$$\begin{aligned} I_{X_{a \leftrightarrow b}}(\sigma^2) &= -\frac{(a-m)^3 f(a; m, \sigma^2) - (b-m)^3 f(b; m, \sigma^2)}{4\sigma^6 A} - \\ &- \frac{3}{4\sigma^4} \left\{ \frac{[(b-m)f(b; m, \sigma^2) - (a-m)f(a; m, \sigma^2)] - A}{A} \right\} - \\ &- \frac{1}{4\sigma^4} \left\{ \frac{[(b-m)f(b; m, \sigma^2) - (a-m)f(a; m, \sigma^2)] - A}{A} \right\}^2, \end{aligned} \quad (5)$$

where

$$f(a; m, \sigma^2), f(b; m, \sigma^2) \in \mathbb{R}^+, \quad (6)$$

*Proof.* We have

$$\begin{aligned} I_{X_{a \leftrightarrow b}}(\sigma^2) &= I_{X_{a \leftrightarrow b}}(\theta) = \\ &= \int_a^b \left( \frac{\partial \ln f_{a \leftrightarrow b}(x; m, \sigma^2)}{\partial \sigma^2} \right)^2 f_{a \leftrightarrow b}(x; m, \sigma^2) dx = \\ &= \int_a^b \left( \frac{\partial \ln f_{a \leftrightarrow b}(x; m, \theta)}{\partial \theta} \right)^2 f_{a \leftrightarrow b}(x; m, \theta) dx. \end{aligned}$$

Using (2) and (3), we obtain

$$\begin{aligned}
 \ln f_{a \leftrightarrow b}(x; m, \sigma^2) &= -\ln \sqrt{2\pi} - \frac{1}{2} \ln \sigma^2 - \ln A - \frac{1}{2} \left( \frac{x-m}{\sigma} \right)^2 = \\
 &= -\ln \sqrt{2\pi} - \frac{1}{2} \ln \theta - \ln \left[ \Phi \left( \frac{b-m}{\sqrt{\theta}} \right) - \Phi \left( \frac{a-m}{\sqrt{\theta}} \right) \right] - \\
 &\quad - \frac{1}{2} \frac{(x-m)^2}{\theta} = \\
 &= \ln f_{a \leftrightarrow b}(x; m, \theta)
 \end{aligned}$$

and, it follows

$$\frac{\partial \ln f_{a \leftrightarrow b}(x; m, \theta)}{\partial \theta} = -\frac{1}{2\theta} - \frac{\frac{\partial}{\partial \theta} \left[ \Phi \left( \frac{b-m}{\sqrt{\theta}} \right) \right] - \frac{\partial}{\partial \theta} \left[ \Phi \left( \frac{a-m}{\sqrt{\theta}} \right) \right]}{A} + \frac{(x-m)^2}{2\theta^2}.$$

Using the relations

$$\begin{aligned}
 \frac{\partial}{\partial \theta} \left[ \Phi \left( \frac{b-m}{\sqrt{\theta}} \right) \right] &= \frac{\partial}{\partial \theta} \left[ \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\frac{b-m}{\sqrt{\theta}}} \exp\left\{-\frac{1}{2}z^2\right\} dz \right] = \\
 &= -\frac{b-m}{2} \frac{1}{\theta^3} \frac{1}{\sqrt{2\pi}} \exp\left\{-\frac{1}{2} \left( \frac{b-m}{\sqrt{\theta}} \right)^2\right\} = \\
 &= -\frac{b-m}{2} \frac{1}{\theta^2} f(b; m, \theta),
 \end{aligned}$$

$$\begin{aligned}
 \frac{\partial}{\partial \theta} \left[ \Phi \left( \frac{a-m}{\sqrt{\theta}} \right) \right] &= \frac{\partial}{\partial \theta} \left[ \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\frac{a-m}{\sqrt{\theta}}} \exp\left\{-\frac{1}{2}z^2\right\} dz \right] = \\
 &= -\frac{a-m}{2} \frac{1}{\theta^2} f(a; m, \theta),
 \end{aligned}$$

it results

$$\begin{aligned}
 \frac{\partial \ln f_{a \leftrightarrow b}(x; m, \theta)}{\partial \theta} &= \frac{\partial \ln f_{a \leftrightarrow b}(x; m, \sigma^2)}{\partial \sigma^2} = \frac{1}{2\sigma^2} \left\{ \frac{(x-m)^2}{\sigma^2} + \right. \\
 &\quad \left. + \frac{[(b-m)f(b; m, \sigma^2) - (a-m)f(a; m, \sigma^2)]}{A} - 1 \right\}
 \end{aligned}$$

and Fisher's information will be written

$$\begin{aligned}
I_{X_{a \leftrightarrow b}}(\sigma^2) &= \int_a^b \left( \frac{\partial \ln f_{a \leftrightarrow b}(x; m, \sigma^2)}{\partial \sigma^2} \right)^2 f_{a \leftrightarrow b}(x; m, \sigma^2) dx = \frac{1}{4\sigma^8 A} \{ I_1 + \\
&+ \sigma^4 \left[ \frac{(b-m)f(b; m, \sigma^2) - (a-m)f(a; m, \sigma^2)}{A} - 1 \right]^2 I_2 + \\
&+ 2\sigma^2 \left[ \frac{(b-m)f(b; m, \sigma^2) - (a-m)f(a; m, \sigma^2)}{A} - 1 \right] I_3 \},
\end{aligned}$$

where

$$\begin{aligned}
I_2 &= \frac{1}{\sqrt{2\pi}\sigma} \int_a^b \exp \left\{ -\frac{1}{2} \left( \frac{x-m}{\sigma} \right)^2 \right\} dx, \\
I_3 &= \frac{1}{\sqrt{2\pi}\sigma} \int_a^b (x-m)^2 \exp \left\{ -\frac{1}{2} \left( \frac{x-m}{\sigma} \right)^2 \right\} dx, \\
I_1 &= \frac{1}{\sqrt{2\pi}\sigma} \int_a^b (x-m)^4 \exp \left\{ -\frac{1}{2} \left( \frac{x-m}{\sigma} \right)^2 \right\} dx.
\end{aligned}$$

By making the change of variables

$$z = \frac{x-m}{\sigma},$$

and, if we consider the formula for integration by parts

$$\int_{\alpha}^{\beta} u dv = uv \Big|_{\alpha}^{\beta} - \int_{\alpha}^{\beta} v du,$$

it results

$$\begin{aligned}
I_2 &= A = \Phi \left( \frac{b-m}{\sigma} \right) - \Phi \left( \frac{a-m}{\sigma} \right), \\
I_3 &= -\sigma^2 \{ [(b-m)f(b; m, \sigma^2) - (a-m)f(a; m, \sigma^2)] - A \}, \\
I_1 &= -\sigma^2 [(b-m)^3 f(b; m, \sigma^2) - (a-m)^3 f(a; m, \sigma^2)] - \\
&\quad - 3\sigma^4 [(b-m)f(b; m, \sigma^2) - (a-m)f(a; m, \sigma^2)] + 3\sigma^4 A.
\end{aligned}$$

Using the final values of the integrals  $I_2$ ,  $I_3$  and  $I_1$ , we obtain (8).  $\square$

## 2. Invariance of the Fisher information

**Corollary 1.** *If  $a = m - \sigma$ ,  $b = m + \sigma$ , then*

$$f_{m-\sigma \leftrightarrow m+\sigma}(x; m, \sigma^2) = \begin{cases} \frac{C(m-\sigma, m+\sigma)}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{1}{2}\left(\frac{x-m}{\sigma}\right)^2\right\} \\ \text{if } m-\sigma \leq x \leq m+\sigma, \\ 0 \text{ if } x < m-\sigma \text{ or } x > m+\sigma, \end{cases} \quad (7)$$

where

$$C(m-\sigma, m+\sigma) = \frac{1}{2\Phi(1) - 1} \approx 2,93 \quad (8)$$

and the Fisher's information measure, relative to the unknown parameter  $\sigma^2$ , has the value

$$I_{X_{m-\sigma \leftrightarrow m+\sigma}}(\sigma^2) \approx 0,03I_X(\sigma^2). \quad (9)$$

*Proof.* Using (8), we obtain

$$\begin{aligned} I_{X_{m-\sigma \leftrightarrow m+\sigma}}(\sigma^2) &= \frac{-2}{4\sigma^4\sqrt{2\pi}e[2\Phi(1) - 1]} - \\ &\quad - \frac{3}{4\sigma^4} \left\{ \frac{2}{\sqrt{2\pi}e[2\Phi(1) - 1]} - 1 \right\} - \\ &\quad - \frac{1}{4\sigma^4} \left\{ \frac{2}{\sqrt{2\pi}e[2\Phi(1) - 1]} - 1 \right\}^2 = \\ &= -\frac{1}{4\sigma^4} \left\{ -3 + \frac{4}{\sqrt{2\pi}e[\Phi(1) - 0,5]} + \right. \\ &\quad \left. + \left( \frac{1}{\sqrt{2\pi}e[\Phi(1) - 0,5]} - 1 \right)^2 \right\} = \\ &= -\frac{1}{4\sigma^4} \{-3 + 2,86 + 0,08\} = \frac{0,03}{2\sigma^4}. \end{aligned}$$

□

**Corollary 2.** (*Invariance of the Fisher information - the first form*) If  $a = m$ ,  $b = m + \sigma$  or if  $a = m - \sigma$ ,  $b = m$ , then

$$f_{m \leftrightarrow m+\sigma}(x; m, \sigma^2) = \begin{cases} \frac{C(m, m+\sigma)}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{1}{2}\left(\frac{x-m}{\sigma}\right)^2\right\} \\ \text{if } m \leq x \leq m+\sigma, \\ 0 \text{ if } x < m \text{ or } x > m+\sigma, \end{cases} \quad (10)$$

and

$$f_{m-\sigma \leftrightarrow m}(x; m, \sigma^2) = \begin{cases} \frac{C(m-\sigma, m)}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{1}{2}\left(\frac{x-m}{\sigma}\right)^2\right\} \\ \text{if } m-\sigma \leq x \leq m, \\ 0 \text{ if } x < m-\sigma \text{ or } x > m, \end{cases} \quad (11)$$

where

$$C(m, m+\sigma) = \frac{1}{\Phi(1) - \Phi(0)} = C(m-\sigma, m) = \frac{1}{\Phi(0) - \Phi(-1)} \approx 2,93 \quad (12)$$

and the Fisher's information measures relative to the unknown parameter  $\sigma^2$  has the same value, namely

$$I_{X_{m \leftrightarrow m+\sigma}}(\sigma^2) = I_{X_{m-\sigma \leftrightarrow m}}(\sigma^2) = \frac{0,03}{2\sigma^4} = I_{X_{m-\sigma \leftrightarrow m+\sigma}}(\sigma^2). \quad (13)$$

**Remark 1.** If we consider the normal variable

$$Y = X - m, \quad (14)$$

then  $E(Y) = 0$ ,  $\text{Var}(Y) = \text{Var}(X) = \sigma^2$  and the probability density function has the form

$$f_Y(y; \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{y^2}{2\sigma^2}}, y \in \mathbb{R}. \quad (15)$$

In this case, the random variable  $Y_{a \leftrightarrow b}$  has a bilateral truncated normal distribution:

$$f_{a \leftrightarrow b}(y; \sigma^2) = \begin{cases} \frac{C_0(a,b)}{\sqrt{2\pi}\sigma} e^{-\frac{y^2}{2\sigma^2}} & \text{if } a \leq y \leq b \\ 0 & \text{if } y < a \text{ or } y > b, \end{cases} \quad (16)$$

where

$$C_0 = C_0(a, b) = \frac{1}{\left[\Phi\left(\frac{b}{\sigma}\right) - \Phi\left(\frac{a}{\sigma}\right)\right]}. \quad (17)$$

Using (8), the Fisher's information measure,  $I_{Y_{a \leftrightarrow b}}(\sigma^2)$  relative to the unknown parameter  $\sigma^2$ , can be written like

$$\begin{aligned} I_{Y_{a \leftrightarrow b}}(\sigma^2) &= \frac{a^3 f_Y(a; \sigma^2) - b^3 f_Y(b; \sigma^2)}{4\sigma^6 C_0} - \\ &- \frac{3}{4\sigma^4} \left[ \frac{b f_Y(b; \sigma^2) - a f_Y(a; \sigma^2)}{C_0} - 1 \right] - \\ &- \frac{1}{4\sigma^4} \left[ \frac{b f_Y(b; \sigma^2) - a f_Y(a; \sigma^2)}{C_0} - 1 \right]^2. \end{aligned} \quad (18)$$

**Corollary 3.** (Invariance of the Fisher information - the second form)

$$\begin{aligned} I_{X_{-\sigma \leftrightarrow \sigma}}(\sigma^2) &= I_{X_{m-\sigma \leftrightarrow m+\sigma}}(\sigma^2) = I_{X_{m \leftrightarrow m+\sigma}}(\sigma^2) = I_{X_{m-\sigma \leftrightarrow m}}(\sigma^2) \approx \\ &\approx \frac{0,03}{2\sigma^4} = 0,03 I_X(\sigma^2). \end{aligned} \quad (19)$$

**Theorem 2.** (Invariance of the Fisher information - the third form) If  $a = m - k\sigma$ ,  $b = m + k\sigma$ , or  $a = -k\sigma$ ,  $b = k\sigma$ , then the probability density function, denoted by  $f_{a \leftrightarrow b}(x; m, \sigma^2)$ , in(2), has the form

$$f_{m-k\sigma \leftrightarrow m+k\sigma}(x; m, \sigma^2) = \begin{cases} \frac{C(m-k\sigma, m+k\sigma)}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{1}{2}\left(\frac{x-m}{\sigma}\right)^2\right\} \\ \text{if } m-k\sigma \leq x \leq m+k\sigma, \\ 0 \text{ if } x < m-k\sigma \text{ or } x > m+k\sigma, \end{cases} \quad (20)$$

or the form

$$f_{-k\sigma \leftrightarrow k\sigma}(x; m, \sigma^2) = \begin{cases} \frac{C(-k\sigma, k\sigma)}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{1}{2}\left(\frac{x}{\sigma}\right)^2\right\} \text{ if } -k\sigma \leq x \leq k\sigma, \\ 0 \text{ if } x < -k\sigma \text{ or } x > k\sigma, \end{cases} \quad (21)$$

where

$$C(m-k\sigma, m+k\sigma) = C(-k\sigma, k\sigma) = \frac{1}{2\Phi(k) - 1}, k \in \mathbb{N}^*. \quad (22)$$

The Fisher's information measures, relative to the unknown parameter  $\sigma^2$ , have the same values

$$\begin{aligned} I_{X_{m-k\sigma \leftrightarrow m+k\sigma}}(\sigma^2) &= I_{X_{-k\sigma \leftrightarrow k\sigma}}(\sigma^2) = -\frac{1}{4\sigma^4} \left\{ -3 + \frac{(k^3 + 3k)}{\sqrt{2\pi}e^{\frac{k^2}{2}} [\Phi(k) - 0,5]} + \right. \\ &\left. + \left( \frac{k}{\sqrt{2\pi}e^{\frac{k^2}{2}} [\Phi(k) - 0,5]} - 1 \right)^2 \right\}, k \in \mathbb{N}^*. \end{aligned} \quad (23)$$

*Proof.* Indeed, using the relations (2), (3) as well as the Theorem 1 and the Corollary 3, we obtain just the above value.  $\square$

**Corollary 4.** (*Invariance of the Fisher information - extended form*)

$$\begin{aligned} I_{X_{m \leftrightarrow m+k\sigma}}(\sigma^2) &= I_{X_{m-k\sigma \leftrightarrow m}}(\sigma^2) = I_{X_{m-k\sigma \leftrightarrow m+k\sigma}}(\sigma^2) = I_{X_{-k\sigma \leftrightarrow k\sigma}}(\sigma^2) = \\ &= -\frac{1}{4\sigma^4} \left\{ -3 + \frac{(k^3 + 3k)}{\sqrt{2\pi}e^{\frac{k^2}{2}}[\Phi(k) - 0, 5]} + \left( \frac{k}{\sqrt{2\pi}e^{\frac{k^2}{2}}[\Phi(k) - 0, 5]} - 1 \right)^2 \right\}, k \in \mathbb{N}^*. \end{aligned} \quad (24)$$

**Remark 2.** *Using Theorem 2 we obtain :*

a) for  $k = 1$ , from (23) it results (19).

b) for  $k = 2$ , from (23) it results

$$\begin{aligned} I_{X_{m-2\sigma \leftrightarrow m+2\sigma}}(\sigma^2) &= I_{X_{-2\sigma \leftrightarrow 2\sigma}}(\sigma^2) = \\ &= -\frac{1}{4\sigma^4} \left\{ -3 + \frac{14}{\sqrt{2\pi}e^2[\Phi(2) - 0, 5]} + \right. \\ &\quad \left. + \left( \frac{3}{\sqrt{2\pi}e^2[\Phi(2) - 0, 5]} - 1 \right)^2 \right\} \approx \end{aligned} \quad (25)$$

$$\begin{aligned} &\approx -\frac{1}{4\sigma^4}(-3 + 1, 6 + 0, 60) = \\ &= \frac{0,40}{2\sigma^4} = 0,40I_X(\sigma^2). \end{aligned} \quad (26)$$

c) for  $k = 3$  we obtain

$$\begin{aligned} I_{X_{m-3\sigma \leftrightarrow m+3\sigma}}(\sigma^2) &= I_{X_{-3\sigma \leftrightarrow 3\sigma}}(\sigma^2) = \\ &= -\frac{1}{4\sigma^4} \left\{ -3 + \frac{36}{\sqrt{2\pi}ee^4[\Phi(3) - 0, 5]} + \right. \\ &\quad \left. + \left( \frac{2}{\sqrt{2\pi}ee^4[\Phi(3) - 0, 5]} - 1 \right)^2 \right\} \approx \end{aligned} \quad (27)$$

$$\approx -\frac{1}{4\sigma^4}(-3 + 0, 33 + 0, 95) = \frac{0,86}{2\sigma^4} = 0,86I_X(\sigma^2). \quad (28)$$



**Conclusion 1.** *The invariance properties of the Fisher information, relative to the unknown parameter  $\sigma^2$ , take place then when the normal variable  $X$  is truncated on intervals of the forms:*

$$[m - k\sigma, m + k\sigma], [m, m + k\sigma], [m - k\sigma, m], [-k\sigma, k\sigma], k \in \mathbb{N}^*. \quad (29)$$

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