

CRITICAL AND VECTOR CRITICAL SETS IN THE PLANE

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Abstract. Given a non-empty set $C \subset \mathbb{R}^2$, is C the set of critical points for some smooth function $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ or vectorial map $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$? In this paper we give some results in this direction.

1. Introduction

A point $p \in \mathbb{R}^2$ is *critical* for a smooth function $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ if its derivative at p is zero. $(df)_p = 0$. This means $\frac{\partial f}{\partial x}(p) = \frac{\partial f}{\partial y}(p) = 0$, in a smooth chart in p . The set of all critical points of f is denoted by $C(f)$. The image of $C(f)$ is the set of *critical values* $B(f) = f(C(f))$. If x is not critical, then it is *regular*. We say that $C \subset \mathbb{R}^2$ is *critical* if $C = C(f)$ for some smooth $f : \mathbb{R}^2 \rightarrow \mathbb{R}$. A *proper function* has the property that $f^{-1}(K)$ is compact for all compact sets K . Equivalently, when $f : \mathbb{R}^2 \rightarrow \mathbb{R}$, $|f(x)| \rightarrow \infty$ iff $|x| \rightarrow \infty$. We say that $C \subset \mathbb{R}^2$ is *properly critical* if f can be chosen to be proper. Clearly, a critical set is closed. What other properties does it have? In the compact case, there is just one other requirement.

Theorem. [No-Pu] *Let C be a compact non-empty subset of \mathbb{R}^2 . The following assertions are equivalent:*

1. C is critical
2. C is properly critical
3. The components of its complement are multiply connected.

A *component* of a topological space is a maximal connected subset of the space. It is *multiply connected* if it is not simply connected. The condition on multiply connectivity is a topological condition on the complement, not on the space. If C is any finite set of points or a Cantor set in the plane, then it is properly critical. Their complements are multiply connected. On the other hand, a circle is not critical. If C

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is the union of a circle and a point, then it is critical if and only if the point is inside the circle.

If its critical set is noncompact, it is unreasonable to expect properness of f . If $C = C(f)$ is closed, unbounded and connected, then by Sard's theorem, f is constant on C , $f(C) = c$, and $f^{-1}(c)$ is noncompact, so f is not proper.

Theorem. *If $C \subset \mathbb{R}^2$ is critical, compact and non-empty, then any bounded component of its complement has disconnected boundary. In particular, no compact curve in \mathbb{R}^2 , smooth or not, is a critical set.*

Given a closed, noncompact set $K \subset \mathbb{R}^2$ when is there a smooth function $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ such that $K = C(f)$? We say that ∞ is *arcwise accessible* in $U \subset \mathbb{R}^2$ if there is an arc $\alpha : [0, \infty) \rightarrow U$ such that $\alpha(t) \rightarrow \infty$ as $t \rightarrow \infty$.

Theorem. [No-Pu] *A closed set $K \subset \mathbb{R}^2$ is critical if and only if ∞ is arcwise accessible in each simply connected component of $\mathbb{R}^2 \setminus K$.*

2. Vector critical sets

Let $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a smooth map. The point $p \in \mathbb{R}^2$ is a *critical point* of f if $\text{rank}_p f \leq 1$. If f is given by $f = (f_1, f_2)$, then in some local chart around p , p is critical point of f if and only if the Jacobi matrix of f in p is singular, which means:

$$\det \begin{bmatrix} \frac{\partial f_1}{\partial x}(x_0, y_0) & \frac{\partial f_1}{\partial y}(x_0, y_0) \\ \frac{\partial f_2}{\partial x}(x_0, y_0) & \frac{\partial f_2}{\partial y}(x_0, y_0) \end{bmatrix} = 0$$

The set $C \subseteq \mathbb{R}^2$ is *vector critical* if it is the critical set of some smooth map $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$. In which conditions will a critical set $C \subset \mathbb{R}^2$ be vector critical? For a class of subsets of the plane, the answer is given by the following theorem:

Theorem. *Any critical set $C \subset \mathbb{R}^2$ is vector critical.*

Proof: Since C is critical, there is a smooth function $f : \mathbb{R}^2 \rightarrow \mathbb{R}$, so that $C = C(f)$, where

$$C(f) = \left\{ (x_0, y_0) \in \mathbb{R}^2 : \frac{\partial f}{\partial x}(x_0, y_0) = \frac{\partial f}{\partial y}(x_0, y_0) = 0 \right\}.$$

Define $F : \mathbb{R}^2 \rightarrow \mathbb{R}^2$, by $F(x, y) = (h(x, y), y)$, where $h : \mathbb{R}^2 \rightarrow \mathbb{R}$ is given by

$$h(x, y) = \int_0^x \left(\left[\frac{\partial f}{\partial x}(x, y) \right]^2 + \left[\frac{\partial f}{\partial y}(x, y) \right]^2 \right) dx.$$

Since h is smooth, so is F . We show that $C(f) = C(F)$.

The Jacobi matrix of f in some point $(x_0, y_0) \in \mathbb{R}^2$ is

$$J(F)(x_0, y_0) = \begin{bmatrix} \left[\frac{\partial f}{\partial x}(x_0, y_0) \right]^2 + \left[\frac{\partial f}{\partial y}(x_0, y_0) \right]^2 & \frac{\partial h}{\partial y}(x_0, y_0) \\ 0 & 1 \end{bmatrix}.$$

For $(x_0, y_0) \in C(f)$, we have $\frac{\partial f}{\partial x}(x_0, y_0) = \frac{\partial f}{\partial y}(x_0, y_0) = 0$, so

$$J(F)(x_0, y_0) = \begin{bmatrix} 0 & \frac{\partial h}{\partial y}(x_0, y_0) \\ 0 & 1 \end{bmatrix}$$

and $(x_0, y_0) \in C(F)$. Conversely, if $(x_0, y_0) \in C(F)$, it follows that $\left[\frac{\partial f}{\partial x}(x_0, y_0) \right]^2 + \left[\frac{\partial f}{\partial y}(x_0, y_0) \right]^2 = 0$, and then $\frac{\partial f}{\partial x}(x_0, y_0) = \frac{\partial f}{\partial y}(x_0, y_0) = 0$, so $(x_0, y_0) \in C(f)$. \square

If, in theorem above f is supposed to be a harmonic function (this means that f has the property $\frac{\partial^2 f}{\partial x^2}(x, y) + \frac{\partial^2 f}{\partial y^2}(x, y) = 0$), then F could be defined to be the map $F = (f, g)$, where $g : \mathbb{R}^2 \rightarrow \mathbb{R}$ is the smooth map which is the solution of the system

$$\begin{cases} \frac{\partial g}{\partial x}(x, y) = -\frac{\partial f}{\partial y}(x, y) \\ \frac{\partial g}{\partial y}(x, y) = \frac{\partial f}{\partial x}(x, y). \end{cases}$$

The converse of this theorem is not true. There are more vector critical sets than critical. A vector critical set which is not critical is the circle in the plane. The map $F : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ given by $F(x, y) = \left(\frac{x^3}{3} + xy - x, y \right)$ is critical exactly on the unit circle in \mathbb{R}^2 .

3. The family of excellent mappings

An *excellent mapping* is a smooth function $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ whose critical points are all folds or cusps. A *fold* is a critical point such that, after smooth local changes of coordinates in the domain and image, the function is of the form

$$f(x, y) = (x^2, y),$$

the critical point being taken to the origin. For a *cusp*, after a change of coordinates, the function is of the form

$$f(x, y) = (xy - x^3, y),$$

where the critical point is taken to the origin.

For an excellent mapping, the set of critical points will consist of smooth curves; we call these *general folds* of the mapping. Also, the cusp points are isolated on the general fold. Let f be an excellent mapping and C a general fold of f through p . Thus p will be a fold point if the image of C near p is a smooth curve with non-zero tangent vector at p , and p will be a cusp point if the tangent vector is zero at p but it becoming non-zero at a positive rate as we move away from p on C .

Let $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be an excellent mapping. The *derivative* of f with respect to V at p is the vector in \mathbb{R}^2

$$\nabla_V f(p) = \lim_{t \rightarrow 0^+} \frac{1}{t} [f(p + tV) - f(p)].$$

For each $p \in \mathbb{R}^2$, consider the vectors $V' = \nabla_V f(p)$ as a function of vectors V with $|V| = 1$. We shall use a certain system of curves defined by f in an open set $R \subset \mathbb{R}^2$. We let R contain p if the vectors V' are not all of the same length. For any $p \in R$, there will be a pair of opposite directions at p such that for V in these directions,

$|V'|$ is a minimum. (For V in the perpendicular direction, $|V'|$ will be a maximum.) Now R is filled up by smooth curves in these directions; we call these curves *curves of minimum* ∇f .

For any $p \in R$ and vector $V \neq 0$, $\nabla_V f(p) = 0$ if and only if p is a singular point and V is tangent to the curve of minimum ∇f .

Consider any general fold curve C . If a curve of minimum ∇f cuts C at a positive angle at p , then for the tangent vector $V(p)$, $\nabla_V f(p) \neq 0$, and hence p is a fold point. Suppose C is tangent to a curve of minimum ∇f at p . Then p is not a fold point, and hence is a cusp point, since f is excellent. Set $V^* = \nabla_V \nabla_V f(p)$; then $V^* \neq 0$. Since $\nabla_V f(p) = 0$, $\nabla_{v'} f(p')$ is approximately in the direction of $\pm V^*$ for p' on C near p . It follows that $\nabla_W f(p)$ is a multiple of V^* , for all vectors W . As we move along the general fold through p , $\nabla_V f(p')$ changes from a negative to a positive multiple of V^* (approximately); hence $V(p')$ cuts the curves of minimum ∇f in opposite senses on the two sides of p . Therefore the curves of minimum ∇f lying on one side of C cut C on both sides of p . We call this side of C the *upper side* and the other the *lower side*.

The image of C has a cusp at $f(p)$, pointing in the direction of $-V^*$. For any vector W not tangent to C at p , $\nabla_W f(p)$ is a positive or negative multiple of V^* , according as W points into the upper or lower side of C .

Let f and g be mappings $\mathbb{R}^2 \rightarrow \mathbb{R}^2$ and $\varepsilon(p)$ a positive continuous function in \mathbb{R} . We say g is an ε -*approximation* to f if

$$|g(p) - f(p)| < \varepsilon(p), \quad \forall p \in \mathbb{R}.$$

If f and g are r -smooth, we say g is an (r, ε) -*approximation* to f if this inequality holds, and also the similar inequalities for all partial derivatives of orders $\leq r$, using fixed coordinate systems. We speak of *general approximations* and *r -approximations* in the two cases.

Let $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be an excellent mapping. We describe certain approximations g to f which have the singularities of f and also further singularities.

(a) *Arbitrary approximations:* For any smooth curve C in the plane which touches no general fold, we may introduce two new folds, one at C and one near C .

For each $p \in C$, let p_t , $-1 \leq t \leq 1$, denote the points of a line segment S_p approximately perpendicular to C in p , with $p_0 = p$. We may choose these segments so that they cover a neighborhood U of C which touches no general fold of f . We change f to obtain g as follows: as t runs from -1 to 1 , let $g(p_t)$ run along $f(S_p)$ from $f(p_{-1})$ to $f(p)$, then back a little, then on through $f(p)$ to $f(p_1)$. If f and C are smooth, we may construct g to be smooth. C is a fold for g and so is a curve C' , consisting of the points $p_{1/2}$, for example. We may let $g = f$ in $\mathbb{R}^2 \setminus U$. With U small enough, g is an arbitrarily good approximation of f .

(b) *Approximations with first derivatives:* Let C_0 be a curve of fold points of f , without cusps. It may be the whole or a part of a complete general fold of f . We show that we may define g to be an arbitrarily good approximation of f together with first derivatives, so that there is a new pair of folds near C_0 . If C_0 is closed, there will be no new cusps for g ; otherwise, the new folds will meet in a pair of cusp points for g .

We may let p_t denote points of a neighborhood of C_0 , as in (a), so that the image of each S_p under f is an arc folded over on itself, the fold occurring at p . Let $g(p_t) = f(p_t)$ for $-1 \leq t \leq 0$; as t runs from 0 to 1 , let $g(p_t)$ move along $f(S_p)$ towards $f(p_1)$, then back a little, and then forward again to $f(p_1)$. So, we obtain two new folds.

We show that we may make g approximate to f near a given point p of C_0 . Then, the approximation is possible near the all of C_0 .

We may choose the coordinates so that f , near p , is given by

$$f(x, y) = (x^2, y).$$

We may define a smooth function $\phi : \mathbb{R} \rightarrow \mathbb{R}$, so that:

1. $\phi(-t) = \phi(t)$, for all $t \in \mathbb{R}$
2. $\phi(0) = 1$
3. $\phi(t) = 0$, for $|t| \geq 1$
4. $0 \leq \phi'(t) \leq \phi'(-\frac{1}{2}) = \alpha$, for $t < 0$.

For $\varepsilon > 0$, define $g : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by

$$g(x, y) = \left(x^2 + \frac{10\varepsilon^2}{\alpha} \phi \left(\frac{x - 2\varepsilon}{\varepsilon} \right), y \right).$$

g is smooth and the Jacobian matrix of g has the form

$$J(g)(x, y) = \begin{bmatrix} 2x + \frac{10\varepsilon}{\alpha} \cdot \phi' \left(\frac{x - 2\varepsilon}{\varepsilon} \right) & 0 \\ 0 & 1 \end{bmatrix}$$

For $x \in (-\infty, \varepsilon] \cup [3\varepsilon, \infty)$, $\phi \left(\frac{x - 2\varepsilon}{\varepsilon} \right) = 0$. So, p is also a critical point of g .

Moreover, as

$$\det J(g)(2\varepsilon, y) = 4\varepsilon + \frac{10\varepsilon}{\alpha} \cdot \phi'(0) = 4\varepsilon > 0$$

$$\det J(g) \left(\frac{5\varepsilon}{2}, y \right) = 5\varepsilon + \frac{10\varepsilon}{\alpha} \cdot \phi' \left(\frac{1}{2} \right) = 5\varepsilon + \frac{10\varepsilon}{\alpha} \cdot (-\alpha) = -5\varepsilon < 0$$

$$\det J(g)(3\varepsilon, y) = 6\varepsilon + \frac{10\varepsilon}{\alpha} \cdot \phi'(1) = 6\varepsilon > 0,$$

then there are two numbers $x_1 \in (2\varepsilon, \frac{5\varepsilon}{2})$ and $x_2 \in (\frac{5\varepsilon}{2}, 3\varepsilon)$, so that

$$\det J(g)(x_1, y) = \det J(g)(x_2, y) = 0 :$$

these define the points of the new folds.

Also, g is an approximation of f with first derivatives:

$$\left| 2x + \frac{10\varepsilon}{\alpha} \phi' \left(\frac{x - 2\varepsilon}{\varepsilon} \right) - 2x \right| = \left| \frac{10\varepsilon}{\alpha} \phi' \left(\frac{x - 2\varepsilon}{\varepsilon} \right) \right| \leq 10\varepsilon, \quad \forall x \in \mathbb{R}.$$

We show now how we may insert cusps. We consider several types of approximation.

(a) *Arbitrarily approximation:* We show that we may insert a pair of nearby arcs where the new function g will have fold points and run them together to give the new cusps.

We consider the smooth curve C , which touches no general fold of f and $p \in C$, as before. Suppose that near the regular point p , f is given by $f(x, y) = (x, y)$. Define ϕ as before and define $g : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by

$$g(x, y) = \left(x + \frac{2\varepsilon}{\alpha} \phi\left(\frac{x}{\varepsilon}\right) \phi\left(\frac{y}{\varepsilon}\right), y \right).$$

Then g is smooth, is an arbitrarily good approximation of f and $g = f$ outside a small neighborhood of p . The critical points of g are those of f and those given by

$$\det J(g)(x, y) = \det \begin{bmatrix} 1 + \frac{2}{\alpha} \phi\left(\frac{y}{\varepsilon}\right) \phi'\left(\frac{x}{\varepsilon}\right) & \frac{2}{\alpha} \phi\left(\frac{x}{\varepsilon}\right) \phi'\left(\frac{y}{\varepsilon}\right) \\ 0 & 1 \end{bmatrix} = 0,$$

or

$$1 + \frac{2}{\alpha} \phi\left(\frac{y}{\varepsilon}\right) \phi'\left(\frac{x}{\varepsilon}\right) = 0.$$

Since $\det J(g)(0, 0) = 1 > 0$, $\det J(g)\left(\frac{\varepsilon}{2}, 0\right) = 1 + \frac{2}{\alpha} \cdot 1 \cdot (-\alpha) = -1 < 0$,

and $\det J(g)(2\varepsilon, 0) = 1 > 0$, it is clear that there are two folds cutting the x -axis. If ϕ is sufficiently simple shape, these come together in two cusps.

(b) *Approximations with first derivatives:* Let p be a fold point of f , on a critical curve of f which contains no cusp points. Near p , f is given by $f(x, y) = (x^2, y)$. We define $g : \mathbb{R}^2 \rightarrow \mathbb{R}^2$, by

$$g(x, y) = \left(x^2 + \frac{10\varepsilon^2}{\alpha} \phi\left(\frac{x-2\varepsilon}{\varepsilon}\right) \phi\left(\frac{y}{\varepsilon}\right) \phi\left(\frac{y}{\varepsilon}\right), y \right),$$

with ϕ chosen as before. Outside a little neighborhood of p , $g = f$. We have

$$J(g)(x, y) = \begin{bmatrix} 2x + \frac{10\varepsilon}{\alpha} \phi'\left(\frac{x-2\varepsilon}{\varepsilon}\right) \phi\left(\frac{y}{\varepsilon}\right) & \frac{\partial g}{\partial y}(x, y) \\ 0 & 1 \end{bmatrix},$$

so $\det J(g)(0, 0) = \frac{10\varepsilon}{\alpha} \phi'(-2) \phi(0) = 0$, which means p is a critical point of g . Since

$$\det J(g)(2\varepsilon, 0) = 4\varepsilon + \frac{10\varepsilon}{\alpha} \phi'(0) \phi(0) = 4\varepsilon > 0$$

$$\det J(g) \left(\frac{5\varepsilon}{2}, 0 \right) = 5\varepsilon + \frac{10\varepsilon}{\alpha}(-\alpha)\phi(0) = -5\varepsilon < 0$$

$$\det J(g)(3\varepsilon, 0) = 6\varepsilon + \frac{10\varepsilon}{\alpha}\phi'(1)\phi(0) = 6\varepsilon > 0,$$

$\det J(g)$ becomes zero for two points of the x -axis. We obtain two new folds, joined at two cusp points, and g is an arbitrarily good approximation of f , together with first derivatives:

$$\begin{aligned} \left| 2x + \frac{10\varepsilon}{\alpha}\phi' \left(\frac{x-2\varepsilon}{\varepsilon} \right) \phi \left(\frac{y}{\varepsilon} \right) - 2x \right| &= \left| \frac{10\varepsilon}{\alpha}\phi' \left(\frac{x-2\varepsilon}{\varepsilon} \right) \phi \left(\frac{y}{\varepsilon} \right) \right| < \\ &< \frac{10\varepsilon}{\alpha} \cdot \alpha \cdot 1 = 10\varepsilon, \quad \forall (x, y) \in \mathbb{R}^2. \end{aligned}$$

(c) *Approximations with first and second derivatives:* Let p be a cusp point of f . Near p , f is given by $f(x, y) = (xy - x^3, y)$. Define g near p by setting

$$g(x, y) = \left(xy - x^3 \left[1 - 2\phi \left(\frac{x}{\varepsilon} \right) \phi \left(\frac{y}{\varepsilon} \right) \right], y \right).$$

Then

$$J(g)(x, y) = \begin{bmatrix} y - 3x^2 \left[1 - 2\phi \left(\frac{x}{\varepsilon} \right) \phi \left(\frac{y}{\varepsilon} \right) \right] + 2x^3 \cdot \frac{1}{\varepsilon} \phi' \left(\frac{x}{\varepsilon} \right) \phi \left(\frac{y}{\varepsilon} \right) & \frac{\partial g}{\partial y}(x, y) \\ 0 & 1 \end{bmatrix}$$

The curve C of general fold of g coincides with the original critical curve C_0 : $y = 3x^2$ of f for $|x| \geq \varepsilon$, it contains p and, by symmetry, is in the x -direction.

Since

$$\frac{\partial f_1}{\partial x}(p) = \frac{\partial f_1}{\partial y}(p) = 0, \quad \frac{\partial^2 f_1}{\partial x^2} \partial x \partial y(p) = 1 \quad \text{și} \quad \frac{\partial^3 f_1}{\partial x^3}(p) = 6,$$

p is a cusp point for g [Wh]. At points of C where $x \leq -\varepsilon$, $g = f$ and

$$J(g)(x, y) \begin{bmatrix} y - 3x^2 & x \\ 0 & 1 \end{bmatrix}, \quad \text{so} \quad \frac{\partial^2 f_1}{\partial x^2}(x, y) = -6x > 0. \quad \text{For } x \geq \varepsilon, \quad g = f \quad \text{and}$$

$$\frac{\partial^2 f_1}{\partial x^2}(x, y) = -6x < 0. \quad \text{On the other hand, since } \frac{\partial^2 f_1}{\partial x^2}(p) = 0 \quad \text{and} \quad \frac{\partial^3 f_1}{\partial x^3}(p) > 0,$$

we have that $\frac{\partial^2 f_1}{\partial x^2}(x, y)$ has the same sign as x for $x \neq 0$ and $|x|$ small enough.

Therefore, as x runs from $-\varepsilon$ to ε , if we run along C , $\frac{\partial J}{\partial x} = \frac{\partial^2 f_1}{\partial x^2}$ changes sign at least three times. With the function ϕ of simple shape, it will change sign exactly three times; that is g will have three cusp points. We have thus introduced two new cusps, the three cusps lying on a single general fold curve.

Differentiating g , it follows that g is an arbitrarily good approximation of f , together with first and second derivatives.

Let $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be an excellent mapping and p a cusp point on the general fold C . Suppose there is a smooth curve A which moves from p to ∞ into the lower side of C and which touches no general fold. Then there is arbitrarily good approximation g to f which agrees with f outside a neighborhood U of A , and for which the part of the fold near p is replaced by a pair of folds going near A , to ∞ , without cusp points.

This may be seen as follows. Around p , f is given by $f(x, y) = (xy - x^3, y)$. Each line $y = a > 0$ is mapped by f so as to fold over on itself twice. The lines $y = a \leq 0$ have no such folds. We need merely insert such folds near the negative y -axis, to join the above folds. These can be extended down along all of A .

We saw that cusps may be eliminated from regions by arbitrarily good approximations. This is not true for folds.

Theorem 3.1. *Let p be a fold point of the excellent mapping f . Then for any neighborhood U of p , each sufficiently good approximation g to f which is excellent has a fold point in U .*

Proof: Since p is a fold point, there are two points p_1 and p_2 in U where the Jacobian has opposite signs. Let U_i be a circular neighborhood of p_i ($i = 1, 2$) which touches no fold, and let U'_i be an interior circular neighborhood. For a sufficiently good approximation g to f , if g_t is the deformation of g into f ,

$$g_t(q) = g(q) + t[f(q) - g(q)] \quad (0 \leq t \leq 1),$$

then the image of the boundary ∂U_i does not touch the image of U'_i under f :

$$g_t(q) \neq f(q'), \quad q \in \partial U_i, \quad q' \in U'_i, \quad 0 \leq t \leq 1.$$

Hence $g(U_i)$ and $f(U_i)$ cover $f(U'_i)$ the same algebraic number of times. For f , this number is ± 1 . Hence there is a point p'_i in U'_i such that the Jacobian of g at p'_i is of

the same sign as the Jacobian of f in U_i . But the Jacobians of g at p'_1 and at p'_2 are of opposite sign. Then the segment $p'_1 p'_2$ contains a singular point of g , and since g is excellent, there is a fold point of g in U . \square

Theorem 3.2. *If Q is a bounded closed set in which f is non-singular, then any sufficiently good approximation g to f is non-singular in Q .*

Proof: It follows since the Jacobian involves only first derivatives. \square

Theorem 3.3. *Let the arc A have end points p_1 and p_2 where f is non-singular. Then, for any sufficiently good 1-approximation g to f which is excellent, any arc A' from p_1 to p_2 which cuts only fold points of f and g cuts the same number of folds (mod 2) for each.*

Proof: This is clear, since the Jacobian of f and of g have the same sign at each p_i . \square

Theorem 3.4. *Let p be a cusp point of f . Then for any neighborhood U of p , each sufficiently good 1-approximation g of f which is excellent has a cusp point in U .*

Proof: There is a curve $A = p_1 p_2 p_3 p_4$ of minimum ∇f in U , which cuts the fold C through p at the points p_2 and p_3 . The open arc $p_2 p_3$ lies in the upper part of C and the open arcs $p_1 p_2$ and $p_3 p_4$ lie in the lower part. There is an arc B from p_1 to p_4 in the lower part of C , lying in U , such that A and B bound a region R' filled by curves of minimum ∇f . For any sufficiently good 1-approximation g to f , there will be an arc A^* of minimum ∇g , near A , which will bound, with part of B , a region R^* filled by curves of minimum ∇g . Also, g will be non-singular in B , and there will be fold points of g in R^* . The set Q of fold and cusp points of g in the closure $\overline{R^*}$ is a closed set. There is a lowest curve D of minimum ∇g in $\overline{R^*}$ which touches Q in a point p^* . Since p^* is not in B , $p^* \in R^*$. p^* is a singular point of g . Also, by definition of D , the general fold of g through p^* does not cross the curve D , and hence is tangent to D . Therefore, p^* is not a fold point of g and it follows that p^* is a cusp point of g . \square

Theorem 3.5. *For any bounded closed set Q in which the only singularities of f are fold points, any sufficiently good 2-approximation g of f which is excellent has only folds in Q .*

Proof: Let p be a fold point of f in Q and let A be a short segment perpendicular to the fold, centered at p . Since $J(f)$ is of opposite signs at the two ends of A , so $F(g)$ will be. Hence $J(g)$ will vanish somewhere on A . Since f is excellent, the directional derivative of $J(f)$ in the direction of A is non-zero, hence the same is true for g and g has just one general fold cutting A . Thus the general folds of g are like those of f in Q , if the 2-approximation is good enough. Since the directions of curves of minimum ∇g and of general folds for g are nearly parallel to the similar curves for f , the conditions for fold points will be satisfied at all general fold points of g in Q , for a good approximation. Hence g will have no cusp points in Q . \square

Theorem 3.6. *Let U be a neighborhood of the cusp point p of f . Then for any sufficiently good 2-approximation g to f which is excellent, there will be a cusp point p' of g in U , on a general fold C' ; there will be no other general folds of g in U , and the number of critical points of g on C' in U will be odd.*

Proof: There will be a unique general fold C' of g in U . At two points p_1, p_2 of the general fold C of f , on opposite sides of p , the curves of minimum ∇f cut C in opposite senses; the same will be true, using g , for similar points p'_1, p'_2 of C' . Hence there will be an odd number of cusps of g between these points. There will be no cusps in $C' \cap U$ outside these points. \square

Theorem 3.7. *With U, p and f as in the last theorem, any sufficiently good 3-approximation g to f has a unique general fold in U , with a unique cusp point on it.*

Proof: There is a unique C' as in the last theorem, with a cusp point p' . Since $\nabla_v \nabla_v f(p) \neq 0$, the similar relation $\nabla_{v'} \nabla_{v'} g(p') \neq 0$ holds. We see that $\nabla_{v'} g$ is in opposite directions on opposite sides of p' on C' , and hence p' is the only cusp of g in U . \square

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