

## SEMILINEAR EQUATIONS IN HILBERT SPACES WITH QUASI-POSITIVE NONLINEARITY

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**Abstract.** The problem is to show that  $Ax + F(x) = 0$  has a solution, where  $A$  is linear, maximal monotone and the nonlinearity  $F$  is a quasi-positive operator of Leray-Schauder type. The existence result is obtained as a consequence of the properties of the Leray-Schauder degree. Finally, some applications are given.

### 1. Introduction

Let  $H$  be a real Hilbert space with the inner product denoted by  $\langle \cdot, \cdot \rangle$  and the corresponding norm

$$\|x\| = \sqrt{\langle x, x \rangle}, \quad x \in H.$$

Let us consider the semilinear equation

$$Ax + F(x) = 0, \tag{1.1}$$

where  $A : D(A) \subset H \rightarrow H$  is a densely defined linear operator and  $N : H \rightarrow H$  is nonlinear. We establish an existence and uniqueness result for the equation (1.1) under some monotonicity conditions. Moreover, assume that  $A$  is maximal monotone. Equations of the form (1.1) arise in natural way in the theory of elliptic equations or integro-differential equations.

An operator  $F : H \rightarrow H$  is called quasi-positive if there exists  $\alpha \in \mathbf{R}$  such that

$$\langle F(x), x \rangle \geq \alpha \|F(x)\|^2, \quad \forall x \in H, x \neq 0. \tag{1.2}$$

This notion is close related with the angle-bounded operators. First, the angle-boundedness concept is defined for linear operators acting from a Banach space

into its dual, then the definition can be extended to nonlinear operators. For details, see [7].

## 2. The Results

We give the following:

**Lemma 2.1.** *If  $F : H \rightarrow H$  is a quasi-positive operator with  $\alpha > 1/2$ , then*

$$\|x - F(x)\| \leq \|x\| \quad , \quad \forall x \in H, x \neq 0.$$

*Proof.* We have:

$$\begin{aligned} \|x - F(x)\|^2 &= \langle x - F(x), x - F(x) \rangle = \\ &= \|x\|^2 - 2 \langle F(x), x \rangle + \|F(x)\|^2 \leq \\ &\leq \|x\|^2 - (2\alpha - 1) \|F(x)\|^2 \leq \|x\|^2. \quad \square \end{aligned}$$

If  $A$  is linear, maximal monotone, then for all  $\lambda > 0$ , the operator  $I + \lambda A$  is invertible with continuous inverse  $(I + \lambda A)^{-1} : H \rightarrow H$  and

$$\|(I + \lambda A)^{-1}\| \leq 1.$$

For proof and further properties, see [3].

Now, the equation (1) can be written as

$$(I + A)x = x - F(x) \Leftrightarrow x = (I + A)^{-1}(x - F(x)),$$

or

$$x = T(x) \Leftrightarrow (I - T)(x) = 0, \tag{2.1}$$

where  $T = (I + A)^{-1}(I - F)$ .

If  $F$  is an operator of Leray-Schauder type, then  $I - F$  is compact and consequently,  $T$  is compact, as the product of a continuous operator with a compact one.

Indeed, if  $D \subset H$  is bounded and  $(x_n)_{n \geq 1} \subset D$ , then there exists  $x$  such that  $(I - F)(x_{k_n}) \rightarrow (I - F)(x)$ , at least on a subsequence. Further,  $(I + A)^{-1}$  is continuous, so  $Tx_{k_n} \rightarrow Tx$ .

In conclusion, the operator  $I - T$  is compact perturbation of the identity map and consequently, the Leray-Schauder degree can be considered.

Roughly speaking, the degree of  $\phi$  at  $y$ , relative to  $D$ , denoted  $d(\phi, D, y)$ , is a measure of the number of the solutions of the equation  $\phi(x) = y$  in  $D$ .

In an infinite dimensional Banach space  $X$ , the Leray-Schauder degree is defined for compact perturbations of the identity map, also named Leray-Schauder operators,  $\phi \in (LS)$ . Some properties of the Leray-Schauder degree are of interest in our work.

**Proposition 2.1.** *Let  $\phi : D \subset X \rightarrow X$  be such that  $I - \phi$  is compact and let  $y \in X \setminus \phi(\partial D)$ . Then the Leray-Schauder degree  $d(\phi, D, y)$  satisfies the following properties:*

(a) *If  $d(\phi, D, y) \neq 0$ , then  $y \in \phi(D)$ .*

(b) *If  $H \in C([0, 1] \times D, X)$  is such that  $I - H(t, \cdot)$  is compact, for all  $t \in [0, 1]$  and  $y \in X \setminus H([0, 1] \times \partial D)$ , then the degree*

$$d(H(t, \cdot), D, y) = \text{constant} \quad , \quad \forall t \in [0, 1].$$

(c) *The degree for the identity map  $I : X \rightarrow X$  is*

$$d(I, D, y) = \begin{cases} 1 & , \quad y \in D \\ 0 & , \quad y \notin D \end{cases} .$$

For more details, see [4], [5].

Now, we can establish the following existence result:

**Theorem 2.1.** *Let  $A : D(A) \subset H \rightarrow H$ ,  $0 \in \text{Int}D(A)$ , linear, maximal monotone and  $F : H \rightarrow H$  be an (LS) - operator such that*

$$\langle F(x), x \rangle \geq \alpha \|F(x)\|^2 \quad , \quad \forall x \in H, x \neq 0,$$

*for some  $\alpha > 1/2$ . Then the equation  $Ax + F(x) = 0$  has at least one solution  $x \in D(A)$ .*

*Proof.* Let  $B = B(0, r)$  be such that  $\overline{B} \subset D(A)$ . We have seen that the equation  $Ax + F(x) = 0$  is equivalent with

$$(I - T)(x) = 0,$$

where  $T = (I + A)^{-1}(I - F)$  is compact.

Let us consider the Leray-Schauder homotopy

$$H(t, x) = x - tT(x) \quad , \quad x \in \overline{B}, t \in [0, 1].$$

If  $0 \in H(1, \partial B)$ , the conclusion follows immediately. In order to use the invariance to homotopy of the Leray-Schauder degree, we prove that  $0 \notin H([0, 1], \partial B)$ . Let us suppose by contrary that  $H(t, x) = 0$ , for some  $x \in \partial B$  and  $t \in [0, 1)$ . It results

$$\begin{aligned} \|x\| &= t \|T(x)\| \leq \|T(x)\| = \|(I + A)^{-1}(I - F)\| \leq \\ &\leq \|(I + A)^{-1}\| \cdot \|x - F(x)\| \leq \|x - F(x)\| \leq \|x\|. \end{aligned}$$

We must have equalities all over, in particular  $T(x) = 0$ . Hence  $x = 0 \in \partial B$ , contradiction. This means that  $0 \notin H([0, 1], \partial B)$  and further,

$$\begin{aligned} d(H(1, \cdot), B, 0) &= d(H(0, \cdot), B, 0) \Rightarrow \\ &\Rightarrow d(I - T, B, 0) = d(I, B, 0) = 1. \end{aligned}$$

In conclusion,  $d(I - T, B, 0) \neq 0$ , thus the equation  $(I - T)(x) = 0$  and equivalent, the equation  $Ax + F(x) = 0$  has at least one solution in  $D(A)$ .  $\square$

### 3. An Application

Now, we are in position to show how the theoretical results from the previous section can be applied to the elliptic boundary value problems.

Let  $\Omega \subset \mathbf{R}^n$  be open, bounded and let  $a_{ij} \in C^1(\overline{\Omega})$ ,  $1 \leq i, j \leq n$  be real valued functions satisfying the ellipticity property

$$\sum_{i,j=1}^n a_{ij} \xi_i \xi_j \geq 0, \quad \forall \xi = (\xi_1, \dots, \xi_n) \in \mathbf{R}^n.$$

Let us consider the following elliptic problem

$$\begin{cases} -\sum_{i,j=1}^n \frac{\partial}{\partial x_j} \left( a_{ij}(t) \frac{\partial x}{\partial x_i} \right) + g(t, x) = 0 & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} \quad (3.1)$$

The particular case  $g(t, x) = a_0(t)x$ , with  $a_0 \in C(\overline{\Omega})$ ,  $a_0 > p > 0$ , is studied in [3], using Lax-Milgram theorem. Some existence results are also obtained in [1] and [2], as a consequence of some general considerations about saddle points. The general case of problem (3.1) is studied in [6], under the assumption that the nonlinear part is strongly monotone.

Here we assume that  $g$  satisfies

$$\int_{\Omega} g(t, x(t)) \cdot x(t) dt \geq \alpha \int_{\Omega} g^2(t, x(t)) dt, \quad (3.2)$$

for some  $\alpha > 1/2$ . Remark that in case  $g(t, x) = a_0(t)x$ , the condition (3.2) is fulfilled with  $\alpha < 1/\|a_0\|$ .

Under the condition (3.2), the problem (3.1) has at least one solution in weak sense. Indeed, we can apply theorem 2.1 in the following functional background:

$$H = L^2(\Omega), \quad Ax = - \sum_{i,j=1}^n \frac{\partial}{\partial x_j} \left( a_{ij}(t) \frac{\partial x}{\partial x_i} \right), \quad D(A) = H^2(\Omega) \cap H_0^1(\Omega)$$

and  $(Fx)(t) = g(t, x)$ . The problem (3.1) can be written in the abstract form

$$Ax + F(x) = 0, \quad x \in D(A) \subset L^2(\Omega).$$

We have:

$$\langle Ax, x \rangle = \int_{\Omega} \sum_{i,j=1}^n a_{ij} \frac{\partial x}{\partial x_j} \cdot \frac{\partial x}{\partial x_i} \geq 0,$$

and  $I + A$  is surjective, e.g. [2], therefore  $A$  is maximal monotone.

Finally, if  $g$  is compact perturbation of the identity, then the assertion is proved.

## References

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