SYLLABUS

1. Information regarding the programme

1.1 Higher education institution	**Babeş-Bolyai University Cluj-Napoca**
1.2 Faculty	**Faculty of Mathematics and Computer Science**
1.3 Department	**Department of Mathematics**
1.4 Field of study	**Mathematics**
1.5 Study cycle	**Bachelor**
1.6 Study programme / Qualification	**Mathematics and Computer Science**

2. Information regarding the discipline

2.1 Name of the discipline (en) (ro)			**Theoretical Mechanics** **Mecanica Teoretica**				
2.2 Course coordinator			**Professor Teodor Grosan**				
2.3 Seminar coordinator			**Professor Teodor Grosan**				
2.4. Year of study	**2**	2.5 Semester	**4**	2.6. Type of evaluation	**E**	2.7 Type of discipline	**DF/Compulsory**
2.8 Code of the discipline		MLE0025					

3. Total estimated time (hours/semester of didactic activities)

3.1 Hours per week	4	Of which: 3.2 course	2	3.3 seminar/laboratory	2
3.4 Total hours in the curriculum	56	Of which: 3.5 course	28	3.6 seminar/laboratory	28
Time allotment:					hours
Learning using manual, course support, bibliography, course notes					22
Additional documentation (in libraries, on electronic platforms, field documentation)					12
Preparation for seminars/labs, homework, papers, portfolios and essays					20
Tutorship					7
Evaluations					8
Other activities:					-

3.7 Total individual study hours	69
3.8 Total hours per semester	125
3.9 Number of ECTS credits	5

4. Prerequisites (if necessary)

4.1. curriculum	• Calculus 2 (Differential and Integral Calculus in $\mathbf{R}^n$); Analytical Geometry; Differential Geometry of Curves and Surfaces;

	• Differential Equations
4.2. competencies	• There are useful logical thinking and mathematical notions and • results from the above mentioned fields

5. Conditions (if necessary)

5.1. for the course	• Classroom with blackboard/video projector
5.2. for the seminar /lab activities	• Classroom with blackboard/video projector

6. Specific competencies acquired

Professional competencies	• C2.3 Application of theoretical methods of analysis adequate to the issue data. • C4.3 Construction of mathematical model using methods, techniques and appropriate tools. • Knowledge of the basic concepts of Mechanics Ability to understand and use fundamental results in geometry, differential and integral calculus, and the theory of differential equations to study particular problems of motion and to provide applications.
Transversal competencies	• CT1 Applying rigorous and effective work rules, manifest responsible attitude to science and teaching, and creative order to maximize their potential in specific situations, the principles and rules of professional ethics. • Ability to apply the studied concepts, to inform themselves, to work independently or in a team in order to carry out studies and to solve complex problems. Ability for continuous self-perfecting and study.

7. Objectives of the discipline (outcome of the acquired competencies)

7.1 General objective of the discipline	• Knowledge, understanding and use of main concepts and results of Mechanics. •
7.2 Specific objective of the discipline	• Acquiring basic and advanced knowledge in Mechanics. • Acquiring basic concepts of kinematics of material point and kinematics of rigid body. • Acquiring basic concepts of dynamics of material point and of systems of material points. • Understanding fundamental problems and results in rigid body dynamics. • Ability to apply and use mathematical models to describe and analyze problems of Mechanics.

	• Knowledge, understanding and use of various topics in mathematics to study problems of Mechanics.

8. Content

8.1 Course	Teaching methods	Remarks
1. Introduction. Fundamental notions of Mechanics. Kinematics of material point: Trajectory, motion equations, velocity and acceleration of material point. Kinematics of material point in Cartesian and intrinsic coordinates (Frénet's coordinate system).	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative explanations.	
2. Curvilinear coordinates. Examples of orthogonal curvilinear coordinates: cylindrical, polar, and spherical coordinates.	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative explanations.	
3. Kinematics of rigid body: Euler's angles. Motion equations. Poisson's formulas.	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative explanations.	
4. The distribution of velocity and acceleration in rigid body. Translational motion of rigid body. Kinematics of rotation of rigid body around a fixed axis. Kinematics of rotation of rigid body around a fixed point.	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative explanations.	
5. General motion of free rigid body. Helical motion. Plane motion of rigid body (I): Pure rotation. Instantaneous centre of rotation.	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative explanations.	
6. Plane motion of rigid body (II): Curves described by the instantaneous centre of rotation. Kinematics of relative motion: definitions, distribution of velocitis and accelerations, Coriolis' formulas, Coriolis' Theorem.	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative explanations.	
7. Dynamics of material point: Newton's laws of Dynamics. Newton's equation. Dynamics of free material point.	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative explanations.	
8. General theorems of dynamics of material point.	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative explanations.	
9. Motion under the influence of a central force. Binet's equation. The case when the central force depends only on the distance: f = f(r).	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative explanations.	
10. The universal attraction law. Newton's problem.	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative	

	explanations.	
11. Dynamics of material point subject to constraints: The motion on a fixed surface, or on a fixed curve. Mathematical pendulum.	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative explanations.	
12. Dynamics of systems of material points. General theorems of dynamics of systems of material points.	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative explanations.	
13. General theorems of the motion of systems of material points around their mass center. Angular momentum and kinetic energy in the fixed axis rigid body motion. Moment of inertia.	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative explanations.	
14. Dynamics of the motion of a rigid body about a fixed point. Considerations on the general motion of a free rigid body.	Lectures, modeling, didactical demonstration, conversation. Presentation of alternative explanations.	

Bibliography

1. Kohr, M., *Special Topics in Mechanics*, Cluj University Press, Cluj- Napoca, 2005 (in Romanian)
2. Brãdeanu, P., *Theoretical Mechanics*, Vols. 1 and 2, Babeş-Bolyai University Press, Cluj-Napoca, 1988 (in Romanian).
3. Iacob, C., *Theoretical Mechanics*, Editura Didactică şi Pedagogică, Bucharest, 1980 (in Romanian)
4. Dragoş, L., *Principles of Analytical Mechanics*, Technical Publishing House, Bucharest, 1976 (in Romanian)
5. Goldstein, H., Poole, C., Safko, J., *Classical Mechanics*, Reading, MA: Addison-Wessley Publ. Co. (3rd edition), 2014
6. Bose, S., Chattoraj, D., *Elementary Analytical Mechanics*, Alpha Science International Ltd. 2000
7. Aaron, F.D., *Analytical Mechanics*, BIC ALL Publishing House, Bucharest, 2002 (in Romanian)
8. Landau, L.D., Lifshitz, E.M., *Mechanics*, Elsevier-Butterworth-Heinemann, (3rd edition), 2005
9. Russo, R., *Classical Problems in Mechanics*, Aracne, Roma, 1997

8.2 Seminar / laboratory	Teaching methods	Remarks
1. Kinematics of material point in Cartesian and orthogonal curvilinear coordinates (cylindrical, shperical, and polar coordinates). Motion in the Frénet coordinate system (I).	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	
2. Kinematics of material point in Cartesian and orthogonal curvilinear coordinates (cylindrical, shperical, and polar coordinates). Motion in the Frénet coordinate system (II).	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	
3. Translational motion of rigid body. Kinematics of rotation of rigid body around a fixed axis.	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	

4. Kinematics of rotation of rigid body around a fixed point. Kinematics of free rigid body.	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	
5. Helical motion. Plane motion of rigid body (I).	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	
6. Plane motion of rigid body (II). Kinematics of relative motion of material point.	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	
7. Dynamics of free material point. Motion of material point in a field of conservative forces.	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	
8. General theorems of dynamics of material point.	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	
9. Central forces (I).	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	
10. Central forces (II).	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	
11. Dynamics of material point subject to constraints. Dynamics of relative motion of material point.	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	
12. Dynamics of systems of material points. Moment of inertia.	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	
13. General theorems of dynamics of systems of material points (I).	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	
14. General theorems of dynamics of systems of material points (II). Dynamics of the motion of a rigid body about a fixed point.	Description of arguments and proofs for solving problems. Direct answers to students. Homework assignments.	

Bibliography

1. Kohr, M., *Special Topics in Mechanics*, Cluj University Press, Cluj- Napoca, 2005 (in Romanian)
2. Turcu, A., Kohr-Ile, M., *Collection of Theoretical Mechanics Problems*, Babeş- Bolyai University Press, Cluj-Napoca, 1993 (in Romanian)
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4. Brãdeanu, P., Pop, I., Bradeanu D., Technical Publishing House, Bucharest, 1979 (in Romanian)
5. Brãdeanu, P., Pop, I., Stan, I., Turcu, A., *Collection of Theoretical Mechanics Problems*, Babeş- Bolyai University Press, Cluj-Napoca, 1976 (in Romanian)
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9. Russo, R., *Classical Problems in Mechanics*, Aracne, Roma, 1997

9. Corroborating the content of the discipline with the expectations of the epistemic community, professional associations and representative employers within the field of the program

The content of this discipline is in accordance with the curricula of the most important universities in Romania and abroad, where the applied mathematics plays an essential role. This discipline is useful in preparing future teachers and researchers in applied mathematics, as well as those who use mathematical models and methods of study in other areas (physics, chemistry, engineering, computer science).

10. Evaluation

Type of activity	10.1 Evaluation criteria	10.2 Evaluation methods	10.3 Share in the grade (%)
10.4 Course	Knowledge of concepts and basic results	Written exam at the end the semester	100%
	Ability to justify by proofs theoretical results		
10.5 Seminar/lab activities	Ability to apply concepts and results acquired in the course in mathematical modeling and analysis of problems in Mechanics		
	There are valid the official rules of the faculty concerning the attendance of students to teaching activities		
10.6 Minimum performance standards			
➢ At least grade 5 (from a scale of 1 to 10) at both written exam			

29.04.2024 Professor Teodor Grosan Professor Teodor Grosan

Grosan Teodor Grosan Teodor

Date of approval Signature of the head of department

30.04.2023 Professor Andrei Marcus